

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# IMSL C Numerical Library 6.0

## User Training

Visual Numerics, Inc. Greater China  
大中華區技術部經理  
劉泰興 Ted Liu  
[ted@vni.com.tw](mailto:ted@vni.com.tw)



## Schedule & Rules

- Session starts at 13:00
- Lecture / Break / Lecture
- Class end around 16:30
- Practice from 16:30 to 17:30
- This class is informal
  - Please ask questions, make comments, discussion, etc.





# Agenda

- What's New in IMSL CNL 6.0
- IMSL CNL Getting Started
- How to Compile and Link IMSL CNL
- IMSL CNL Inside
- Open Discussion

# About Visual Numerics

*Company*

- Leader in advanced numerical analysis and visualization software
- Established 1970; privately held
- Direct sales, support, and distributor channels worldwide

*Products &  
Services*

- Embeddable mathematical and statistical algorithms for a broad range of applications
- Visualization software for data-intensive, production applications
- Consultants with unique expertise in computational science and algorithm development

*Customers &  
Partners*

- Over 500,000 users worldwide
- Core markets in high performance computing (HPC), finance and business analytics
- Long-term relationships with top tier technology partners

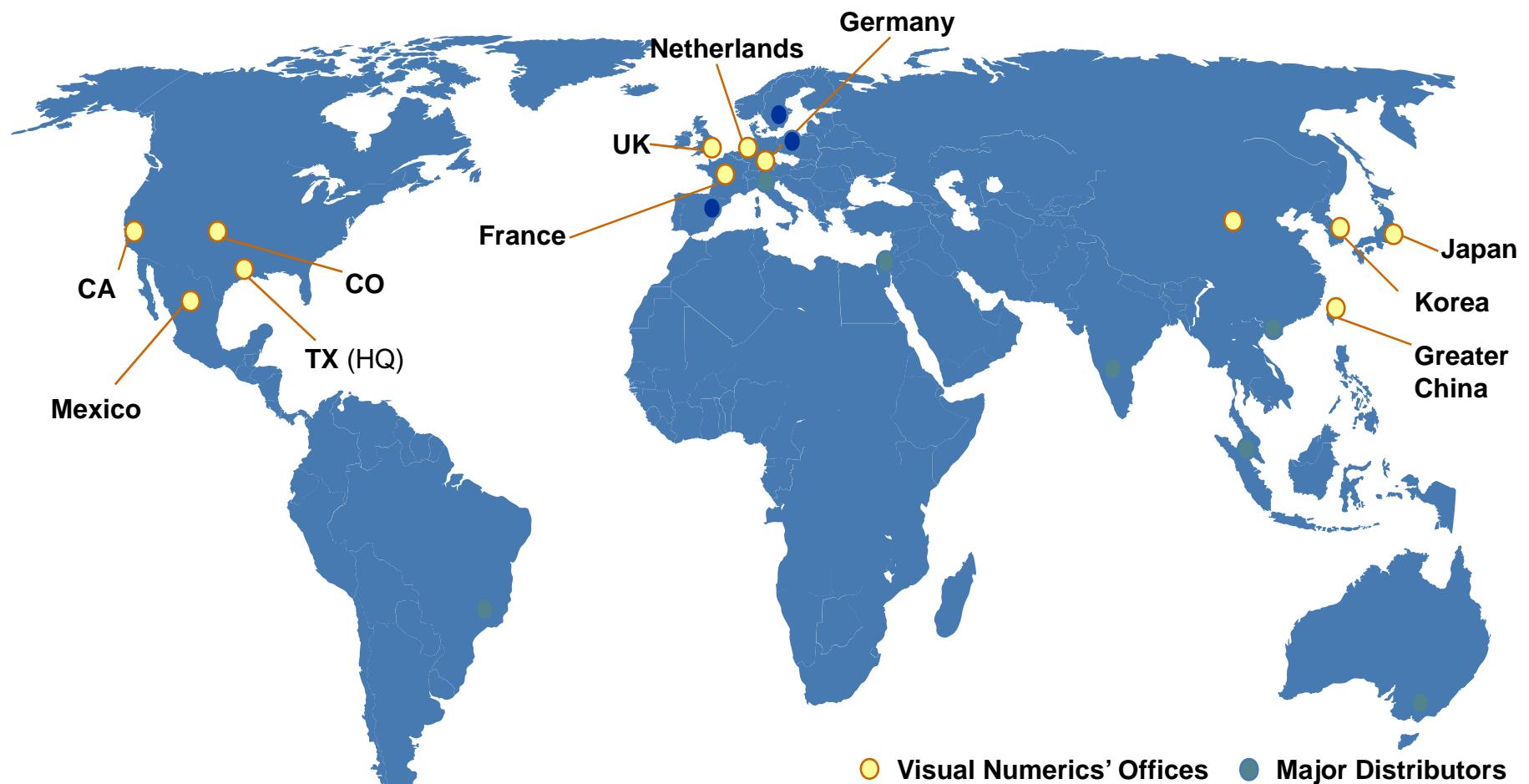


# Visual Numerics, Inc. History

- 1970
  - IMSL, Inc. (Texas, USA)
- 1980
  - Precision Visuals, Inc. (Colorado, USA)
- 1993
  - IMSL, Inc. and Precision Visuals, Inc. merged to Visual Numerics, Inc.
- 1995
  - Visual Numerics, Inc. Greater China established
- 2007
  - 37th Anniversary

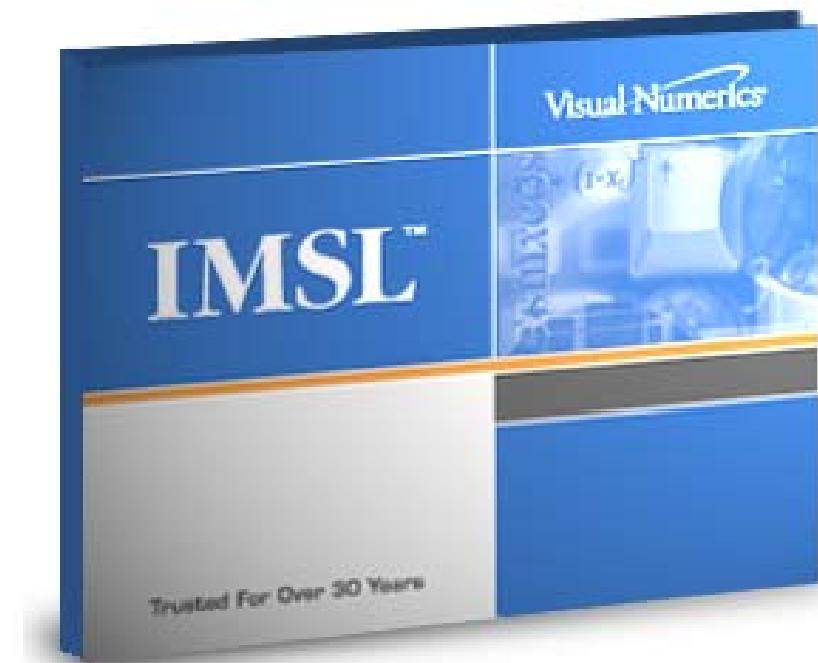


# Visual Numerics Global Footprint





# IMSL™ Numerical Libraries for C, C#, Java™, and Fortran



- Comprehensive libraries of mathematical, statistical, and financial numerical algorithms
- Embeddable code eliminates the need to write code from scratch
- High-performance computing and expertise for developing and executing sophisticated numerical applications
- Trusted for over 30 years

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# New in IMSL C Numerical Library 6.0



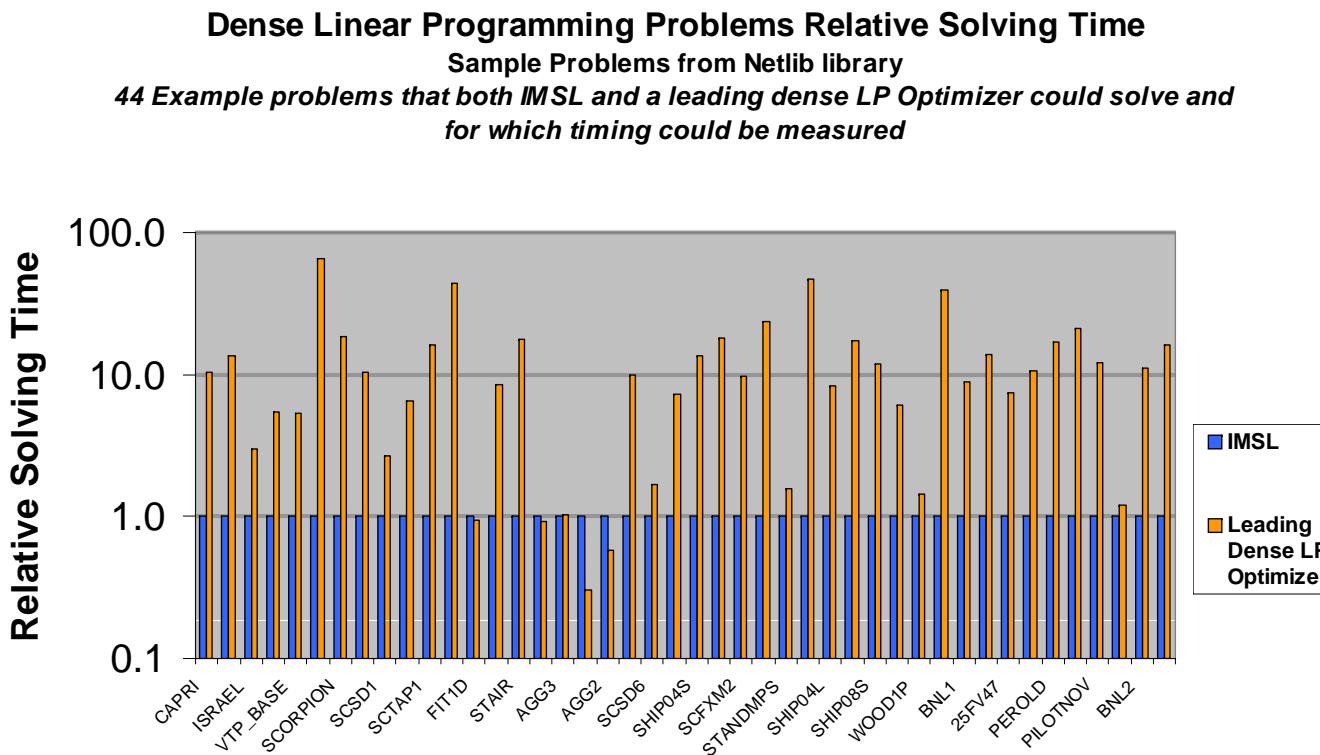
## New for IMSL CNL 6.0 Linear Programming

- World's fastest dense Linear Programming Optimizer in a general math library
- World's most robust dense Linear Programming Optimizer in a general math library
- MPS reader
  - Common file format for optimization problems



# New for IMSL CNL 6.0 Linear Programming Speed

- Extensive testing on a suite of test cases from Netlib  
(<http://www-fp.mcs.anl.gov/otc/Guide/TestProblems/LPtest/>)

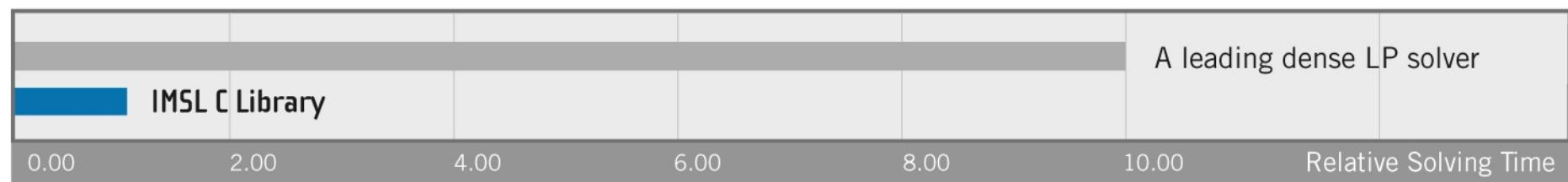




## New for IMSL CNL 6.0 Linear Programming Speed

- Over 10 times faster than a leading dense Linear Programming Optimizer

Average Solving Time For IMSL Versus a Competitive Dense LP Solver (44 Measurable Example Problems)



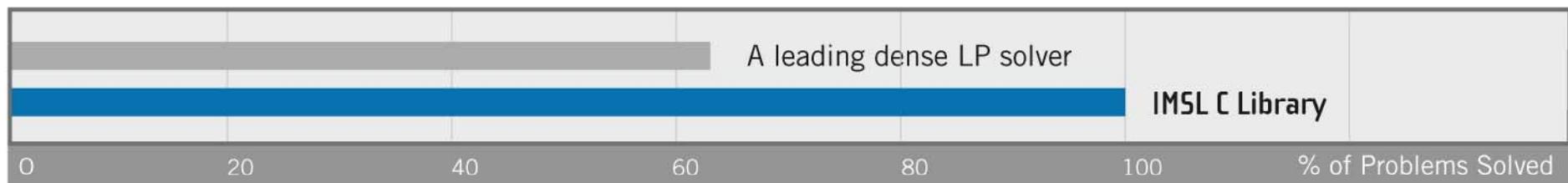
IMSL C Library solves linear programming problems in 1/10 the time.



## New for IMSL CNL 6.0 Linear Programming Robustness

- 91 problems attempted by IMSL and another LP Optimizer
  - IMSL solved 91, failed on 0
  - Other dense LP Optimizer solved 56, failed on 35
- IMSL provides clear diagnostics if problem is infeasible
  - A Leading dense LP Optimizer keeps plugging away without indication of status
  - Can take more hours until user finally gives up

Problems Solved for Dense LP Solvers



IMSL C Library solves 100% of sample Netlib problems.

# New for IMSL CNL 6.0 Forecasting Package

- Neural Network
  - Data pre-conditioners
  - Trainer
  - Forecasting engine
- AutoARIMA forecasting algorithm
  - Automatically identifies outliers, classifies outliers, and estimates missing values
- Time-series data pre-conditioners
  - Outlier detection
  - Outlier classification
  - Missing value estimation
- Stand-alone pre-conditioners



## New for IMSL CNL 6.0

# Mersenne Twister / PDE

- Mersenne Twister
  - Fast, efficient
  - Very high-quality random numbers
  - Long Period
  - Chance of any detectable pattern is reduced
  - Developed 1996-1997 in Japan (Makoto Matsumoto & Takuji Nishimura)
- Partial Differential Equations
  - dea\_petzold\_gear
    - Solution of Differential-Algebraic Systems using Petzold-Gear method
  - pde\_1d\_mg
    - Solves a system of one-dimensional time-dependent partial differential equations using a moving-grid interface



# IMSL CNL 6.0 Ports on Windows & Linux

| Operation System        | Compiler Version  |
|-------------------------|---|
| Windows 32-bit (x86-32) | <b>MSVS 2005</b><br><b>MSVS .NET 2003</b><br><b>MSVC++ 6.0</b><br><b>Intel 9.0</b>  |
| Windows 64-bit (x86-64) | <b>Opteron Intel 9.0</b><br><b>Opteron MS SDK</b><br><b>EM64T Intel 9.0</b><br><b>EM64T MS SDK</b>  |
| Linux 32-bit (x86-32)   | <b>RH4 gcc 3.4.3</b><br><b>RH4 Intel 9.1</b><br><b>Mac OSX 10.4.8 gcc 4.0.1</b>   |
| Linux 64-bit (x86-64)   | <b>Opteron RH 4 gcc3.4.3</b><br><b>Opteron SuSE 9 gcc3.3.3 (SuSE10 gcc 4.1.0 OK)</b><br><b>Opteron SuSE 9 Portland pgcc 6.0-5</b><br><b>EM64T SuSE 9 3.3.3</b><br><b>EM64T RH 4 gcc3.4.4</b><br><b>EM64T RH 4 Intel 9.1</b> |
| Linux 64-bit (Itanium2) | <b>Red Hat EL 4.0 Intel 9.0</b><br><b>SuSE 9 Intel 9.0</b><br><b>VMS 8.3 C 7.1.011</b>  |



## New for IMSL CNL 6.0 LAPACK Integration

- Many of the codes in the IMSL C Numerical Library are based on **LINPACK** and **EISPACK**
  - Designed in the 1970s and early 1980s
- LAPACK (1999) <http://www.netlib.org/lapack> was designed to make the linear solvers and eigensystem routines run more efficiently on high performance computers
- IMSL C Library has the option of linking to code which is based on either the legacy routines or the more efficient LAPACK routines



# New for IMSL CNL 6.0 LAPACK Integration

| Single Precision IMSL Library Routine | LAPACK Routines used when Linking with Name       |
|---------------------------------------|---|
| imsl_c_eig_gen                        | ?geevx_, ?=c/z                                    |
| imsl_c_eig_herm                       | ?heevx_, ?=c/z                                    |
| imsl_c_geneig                         | ?ggev_, ?=c/z                                     |
| imsl_c_lin_sol_gen                    | ?getrs_, ?getrf_, ?gecon_, ?getri_, ?=c/z         |
| imsl_c_lin_sol_gen_band               | ?gbcon_, ?gbtrf_, ?gbtrs_, ?=c/z                  |
| imsl_c_lin_sol_posdef                 | ?potri_, ?potrf_, ?pocon_, ?potrs_, ?=c/z         |
| imsl_c_lin_sol_posdef_band            | ?pbcon_, ?pbtrf_, ?pbtrs_, ?=c/z                  |
| imsl_c_lin_svd_gen                    | ?gesvd_, ?=c/z                                    |
| imsl_f_bounded_least_squares          | ?ormqr_, ?=s/d                                    |
| imsl_f_eig_gen                        | ?geevx_, ?=s/d                                    |
| imsl_f_eig_sym                        | ?yevx_, ?=s/d                                     |
| imsl_f_eig_symgen                     | ?sygv_, ?=s/d                                     |
| imsl_f_geneig                         | ?ggev_, ?=s/d                                     |
| imsl_f_lin_least_squares_gen          | ?orgqr_, ?geqrf_, ?geqp3_, ?ormqr_, ?trsm_, ?=s/d |
| imsl_f_lin_sol_gen                    | ?getrs_, ?getrf_, ?gecon_, ?getri_, ?=s/d         |
| imsl_f_lin_sol_gen_band               | ?gbcon_, ?gbtrf_, ?gbtrs_, ?=s/d                  |
| imsl_f_lin_sol_posdef                 | ?pocon_, ?potrf_, ?potri_, ?=s/d                  |
| imsl_f_lin_svd_gen                    | ?gesvd_, ?=s/d                                    |
| imsl_f_nonlin_least_squares           | ?ormqr_, ?=s/d                                    |
| imsl_f_pde_1d_mg_mgr                  | ?gbtrf_, ?=s/d                                    |



## IMSL CNL Vendor BLAS

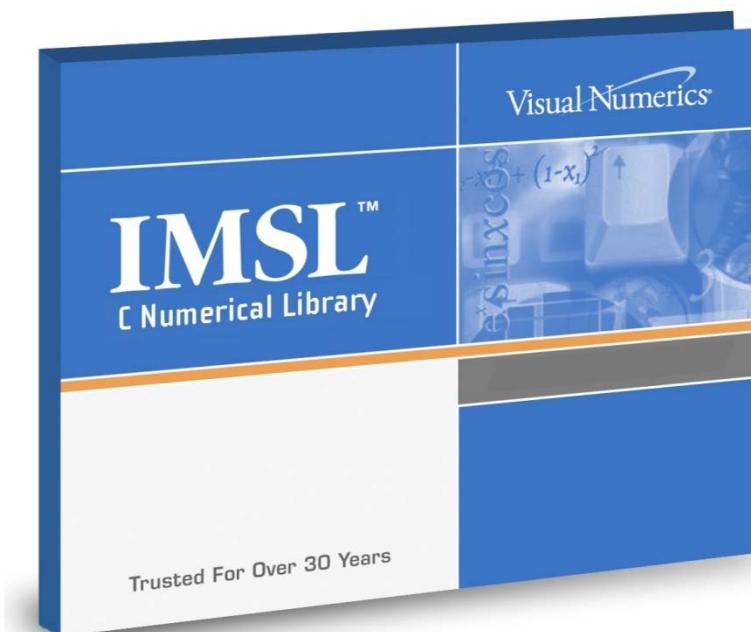
- Basic Linear Algebra Subroutines  
<http://www.netlib.orgblas/>
  - Level 1: vector-vector operations
  - Level 2: matrix-vector operations
  - Level 3: matrix-matrix operations
- A user-supplied BLAS library is required using the SMP linking options
  - Set **OMP\_NUM\_THREADS** to set the number of CPUs
- Expanded support
  - IMSL has some functions that use vendor BLAS

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# IMSL CNL Getting Started



# IMSL C Numerical Library



- Thread-Safe
- SMP High-Performance Technology
- 100% Pure C Code
- Cost-Effectiveness and Value
- Intuitive Programming
- Diagnostic Error Handling
- Fully tested and qualified for popular hardware, operating systems, and compilers



## IMSL License Types

- Development / Run-Time
- Object code / Source code
- Node-Locked / Floating
- Campus and Department Annual Licenses
- Evaluation

# IMSL C Library History

| Year | Major Release  |
|------|--|
| 1990 | 1st release of IMSL C library (Ver.1.0 – Math)   |
| 1991 | Ver.1.0 - Stat release   |
| 1995 | Ver.2.0 release (included library for C++)   |
| 1998 | Ver.2.5 release  |
| 1999 | Ver.3.0 release  |
| 2000 | Ver.4.0 release (100% thread safe)   |
| 2001 | Ver.5.0 release<br>Kalman filter, QMC, Faure sequence, finance & bond  |
| 2003 | Ver.5.5 release<br>NLP, enhancement of time-series and multivariate analysis, DOE                            |
|      | Ver.6.0 release  |
| 2006 | Fast LP, AutoARIMA, neural network, time-series data pre-conditioner, Mersenne Twister random number, LAPACK |



# IMSL CNL MATH Functions

1. Linear Systems
2. Eigensystem Analysis
3. Interpolation and Approximation
4. Quadrature
5. Differential Equations
6. Transforms
7. Nonlinear Equations
8. Optimization
9. Special Functions
10. Statistics and Random Number Generation
11. Printing Functions
12. Utilities



# IMSL CNL STAT Functions

1. Basic Statistics
2. Regression
3. Correlation and Covariance
4. Analysis of Variance and Designed Experiments
5. Categorical and Discrete Data Analysis
6. Nonparametric Statistics
7. Tests of Goodness-of-Fit
8. Time Series and Forecasting
9. Multivariate Analysis
10. Survival and Reliability Analysis
11. Probability Distribution Functions and Inverses
12. Random Number Generator
13. Neural Networks
14. Printing Functions
15. Utilities



# IMSL CNL 6.0 Directory Layout UNIX Versus Windows

<VNI\_DIR> (/opt/vni/)

```
|  
| — license  
|   | — bin  
|   | — bin.rs6000  
| — imsl  
|   | — cnl600  
|     | — help  
|     | — itanium  
|     | — bin  
|     | — examples  
|     | — include  
|     | — lib  
|     | — notes
```

<VNI\_DIR> (C:\Program Files\VNI)

```
|  
| — license  
|   | — bin  
|   | — bin.i386nt  
| — imsl  
|   | — cnl600  
|     | — help  
|     | — vs05pc  
|       | — bin  
|       | — examples  
|       | — include  
|       | — lib  
|       | — notes
```

# IMSL CNL Naming Conventions 1/3

- Most functions are available in both a type *float* and a type *double* version, with names of the two versions sharing a common root
- The section names for the functions only contain the common root to make finding the functions easier
- For example
  - lin\_sol\_gen (common root)
    - imsl\_f\_lin\_sol\_gen
    - imsl\_d\_lin\_sol\_gen

## IMSL CNL Naming Conventions 2/3

- Same variable name is used consistently throughout the IMSL
- For example
  - In the functions for eigensystem analysis
    - eval
      - the vector of eigenvalues
    - n\_eval
      - the number of eigenvalues computed or to be computed



# IMSL CNL Naming Conventions 3/3

| C Math Library |         |
|----------------|---------|
| Type           | Prefix  |
| float          | imsl_f_ |
| double         | imsl_d_ |
| int            | imsl_i_ |
| f_complex      | imsl_c_ |
| d_complex      | imsl_z_ |

| C Stat Library |          |
|----------------|----------|
| Type           | Prefix   |
| float          | imsls_f_ |
| double         | imsls_d_ |
| int            | imsls_i_ |

Data type

Math or Stat

imsl\_f\_lin\_sol\_gen

Common Root

- Do not choose a name beginning with “imsls\_” or “imsl\_” in any combination of uppercase or lowercase characters

# IMSL CNL Include File

- Located at /opt/vni/imsl/cnl600/include
- Specify at the top of the program
  - C/MATH            - #include <imsl.h>
  - C/STAT            - #include <imsls.h>



# IMSL CNL Arguments

- Use of optional argument
- The last argument is always 0

Required argument

Last argument is 0

```
x = imsl_f_lin_sol_gen (n, a, b, IMSL_INVERSE, &p_inva, 0);
```

Optional argument

Value of optional argument



# IMSL CNL

## How to Find the Right Routine

- Locate in each chapter introduction
  - Table of contents located in chapter introduction
  - Alphabetical “Summary of Functions”
- Each routine in the document has at least one example demonstrating its application





# IMSL CNL Manual Organization

## Example: LIN\_SOL\_GEN 1/5

### lin\_sol\_gen

Solves a real general system of linear equations  $Ax = b$ . Using optional arguments, any of several related computations can be performed. These extra tasks include computing the LU factorization of  $A$  using partial pivoting, computing the inverse matrix  $A^{-1}$ , solving  $A^T x = b$ , or computing the solution of  $Ax = b$  given the LU factorization of  $A$ .

### Synopsis

```
#include <imsl.h>
float *imsl_f_lin_sol_gen (int n, float a[], float b[], ..., 0)
```

The type double procedure is `imsl_d_lin_sol_gen`.

### Required Arguments

*int n (Input)*

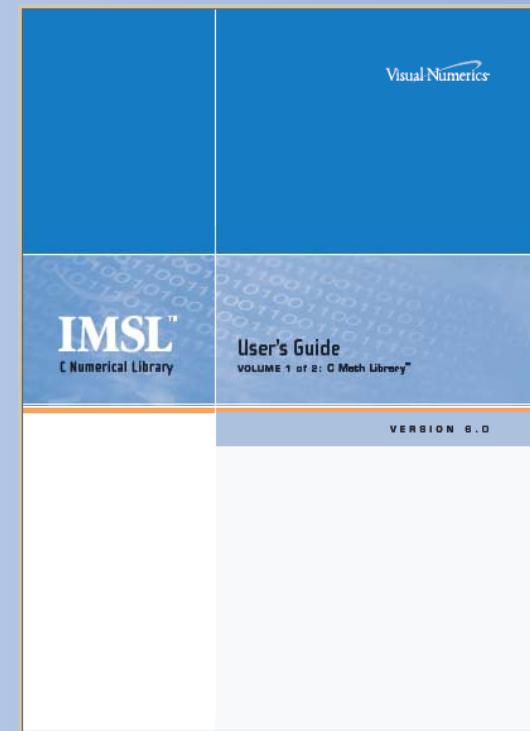
Number of rows and columns in the matrix.

*float a[] (Input)*

Array of size  $n \times n$  containing the matrix.

*float b[] (Input)*

Array of size  $n$  containing the right-hand side.





# IMSL CNL Manual Organization

## Example: LIN\_SOL\_GEN 2/5

### Return Value

A pointer to the solution  $x$  of the linear system  $Ax = b$ . To release this space, use `free`. If no solution was computed, then `NULL` is returned.

### Synopsis with Optional Arguments

```
#include <imsl.h>
float *imsl_f_lin_sol_gen (int n, float a[], float b[],
                           IMSL_A_COL_DIM, int a_col_dim,
                           IMSL_TRANSPOSE,
                           IMSL_RETURN_USER, float x[],
                           IMSL_FACTOR, int **p_pvt, float **p_factor,
                           IMSL_FACTOR_USER, int pvt[], float factor[]),
                           IMSL_FAC_COL_DIM, int fac_col_dim,
                           IMSL_INVERSE, float **p_inva,
                           IMSL_INVERSE_USER, float inva[],
                           IMSL_INV_COL_DIM, int inva_col_dim,
                           IMSL_CONDITION, float *cond,
                           IMSL_FACTOR_ONLY,
                           IMSL_SOLVE_ONLY,
                           IMSL_INVERSE_ONLY,
                           0)
```



# IMSL CNL Manual Organization

## Example: LIN\_SOL\_GEN 3/5

### Optional Arguments

`IMSL_A_COL_DIM, int a_col_dim (Input)`

The column dimension of the array a.

Default: `a_col_dim = n`

`IMSL_TRANSPOSE`

Solve  $ATx = b$ .

Default: Solve  $Ax = b$

`IMSL_RETURN_USER, float x[] (Output)`

A user-allocated array of length  $n$  containing the solution  $x$ .

:

### Description

The function `imsl_f_lin_sol_gen` solves a system of linear algebraic equations with a real coefficient matrix A. It first computes the LU factorization of A with partial pivoting such that  $L^{-1}A = U$ . The matrix U is upper triangular, while  $L^{-1}A \equiv P_n \ L_{n-n}P_{n-1} \dots L_1P_1A \equiv U$ . The factors  $P_i$  and  $L_i$  are defined by the partial pivoting. Each  $P_i$  is an interchange of row  $i$  with row  $j \geq i$ . Thus,  $P_i$  is defined by that value of  $j$ . Every

$$L_i = I + m_i e_i^T$$

is an elementary elimination matrix. The vector  $m_i$  is zero in entries 1, ...,  $i$ . This vector is stored as column  $i$  in the strictly lower-triangular part of the working array containing the decomposition information.



# IMSL CNL Manual Organization

## Example: LIN\_SOL\_GEN 4/5

### Example 1

This example solves a system of three linear equations. This is the simplest use of the function. The equations follow below:

$$\begin{aligned}x_1 + 3x_2 + 3x_3 &= 1 \\x_1 + 3x_2 + 4x_3 &= 4 \\x_1 + 4x_2 + 3x_3 &= -1\end{aligned}$$

```
#include <imsl.h>
main()
{
    int n = 3;
    float *x;
    float a[] = {1.0, 3.0, 3.0,
                 1.0, 3.0, 4.0,
                 1.0, 4.0, 3.0};
    float b[] = {1.0, 4.0, -1.0};
    /* Solve Ax = b for x */
    x = imsl_f_lin_sol_gen (n, a, b, 0);
    /* Print x */
    imsl_f_write_matrix ("Solution, x, of Ax = b", 1, 3, x, 0);
}
```



# IMSL CNL Manual Organization

## Example: LIN\_SOL\_GEN 5/5

### Output

Solution,  $x$ , of  $Ax = b$

|    |    |   |
|----|----|---|
| 1  | 2  | 3 |
| -2 | -2 | 3 |

### Warning Errors

**IMSL\_ILL\_CONDITIONED** The input matrix is too ill-conditioned. An estimate of the reciprocal of its *L1 condition number* is “rcond” = #. The solution might not be accurate.

### Fatal Errors

**IMSL\_SINGULAR\_MATRIX** The input matrix is singular.

# How to Get Help?

- Visual Numerics Forums
  - <http://www.vni.com.tw/forums/> (Chinese Version)
  - <http://forums.vni.com/> (English Version)
- Search the on-line Tips Database
  - <http://www.vni.com/tech/imsl/tips.html>
- Useful documents in Taiwan Support Center
  - <http://www.vni.com.tw/tw/tech/imsl/>
- Live Resources
  - Phone Support
    - Open Monday ~ Friday 09:00 AM ~ 18:00 PM
    - Phone Number 886-2-2727-2255
    - Fax Number 886-2-2727-6798
  - Email Support
    - E-mail (Taiwan) [imsl@vni.com.tw](mailto:imsl@vni.com.tw)

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# How to Compile and Link IMSL CNL



# Setup IMSL CNL Environment UNIX

- C shell users:
  - [source /opt/vni/imsl/cnl600/itanium/bin/cnlsetup.csh](#)
- Bourne and Korn shell users:
  - [./opt/vni/imsl/cnl600/itanium/bin/cnlsetup.sh](#)
- It is recommended that the setup procedure be executed automatically each time you login rather than having to do it interactively
  - By adding the command (**source** and **.**) to the
    - **.cshrc** (for C shell)
    - **.profile** (for sh, ksh)
- USTC HP cluster already setup IMSL environment for users

# Setup IMSL CNL Environment Windows



- Setting MS Visual Studio 2005 environment variables
  - 開始 → 所有程式 → Microsoft Visual Studio 2005 → Visual Studio Tool → Visual Studio 2005 命令提示字元
- Setting IMSL CNL V6.0 environment variables
  - C:\Program Files\VNI\IMSL\CNL600\vs05PC\BIN\CNLSETUP.bat

# Environment Variables

| Environment variable  | Description   |
|-----------------------|---|
| \$CC                  | C compiler  |
| \$CFLAGS              | C Compiler Options<br>does not include any optimization or debugging options  |
| \$LINK_CNL_SHARED     | Link options required to link with the <a href="#">shared libraries</a> version of the C Numerical Library  |
| \$LINK_CNL_STATIC     | Link options required to link with the <a href="#">static libraries</a> version of the C Numerical Library  |
| \$LINK_CNL_SHARED_SMP | Link options required to link with the <a href="#">shared libraries</a> version of the C Numerical Library. This option links with the supported vendor <a href="#">BLAS</a> and <a href="#">LAPACK</a> libraries |
| \$LINK_CNL_STATIC_SMP | Link options required to link with the <a href="#">static libraries</a> version of the C Numerical Library. This option links with the supported vendor <a href="#">BLAS</a> and <a href="#">LAPACK</a> libraries |
| \$LINK_CNL            | By default, set to \$LINK_CNL_SHARED  |
| \$LINK_CNL_SMP        | By default, set to \$LINK_CNL_SHARED_SMP  |



# Environment Variables

## UNIX – IBM Example

- echo \$CFLAGS
  - -q64 -DANSI -I/usr/local/imsl/cnl600/rs6000\_64/include
  - Does not include any optimization or debugging options
- echo \$LINK\_CNL
  - -L/usr/local/imsl/cnl600/rs6000\_64/lib -brtl -bdynamic -limslcmath\_r -limslcmath\_scalar\_r -limslcmath\_iblas\_r -limslcstat\_r -limslcstat\_iblas\_r -lm\_r
- echo \$LINK\_CNL\_STATIC
  - -L/usr/local/imsl/cnl600/rs6000\_64/lib -brtl -bstatic -limslcmath\_r -limslcmath\_scalar\_r -limslcmath\_iblas\_r -limslcstat\_r -limslcstat\_iblas\_r -limslcmath\_r -limslcmath\_scalar\_r -limslcmath\_iblas\_r -limslcstat\_r -limslcstat\_iblas\_r -bdynamic -lm\_r
- echo \$LINK\_CNL\_SMP
  - -L/usr/local/imsl/cnl600/rs6000\_64/lib -brtl -bdynamic -limslcmath\_r -limslcmath\_smp\_r -limslcmath\_vblas\_r -limslcstat\_r -limslcstat\_vblas\_r -**limsllapack\_r** -bstatic -lesslsmmp -bdynamic -lxlf90\_r -lxlsmp -lm\_r

# Environment Variables Windows



- echo %LINK\_CNL\_SHARED%
  - -DANSI -MD **imslcmath\_dll.lib imslcstat\_dll.lib** msvcrt.lib kernel32.lib user32.lib netapi32.lib advapi32.lib gdi32.lib comdlg32.lib comctl32.lib
- echo %LINK\_CNL\_STATIC%
  - -DANSI imslcmath.lib imslcmath\_scalar.lib **imslcmath\_iblas.lib imslcstat.lib imslcstat\_iblas.lib Imgr.lib** libcrvs.lib libsb.lib libcmtd.lib oldnames.lib kernel32.lib user32.lib netapi32.lib advapi32.lib gdi32.lib comdlg32.lib comctl32.lib wsock32.lib /link /nodefaultlib:libc.lib /nodefaultlib:libcd.lib /opt:noref
- echo %LINK\_CNL\_SHARED\_SMP%
  - -DANSI -MD **imslcmath\_mkl\_dll.lib imslcstat\_mkl\_dll.lib** msvcrt.lib kernel32.lib user32.lib netapi32.lib advapi32.lib gdi32.lib comdlg32.lib comctl32.lib
- echo %LINK\_CNL\_STATIC\_SMP%
  - -DANSI imslcmath.lib imslcmath\_smp.lib imslcmath\_vblas.lib imslcstat.lib imslcstat\_vblas.lib Imgr.lib libcrvs.lib libsb.lib mkl\_c.lib libcmtd.lib oldnames.lib kernel32.lib user32.lib netapi32.lib advapi32.lib gdi32.lib comdlg32.lib comctl32.lib wsock32.lib /link /nodefaultlib:libc.lib /nodefaultlib:libcd.lib /opt:noref



# Compiling and Linking CNL UNIX

- The following command will compile and link an application program
  - **\$CC -o <executable> \$CFLAGS <main> \$LINK\_CNL**
- **\$LINK\_CNL** can easily be replaced by any of the **\$LINK\_CNL\*** variables
  - **\$LINK\_CNL\_SHARED**
  - **\$LINK\_CNL\_STATIC**
  - **\$LINK\_CNL\_SHARED\_SMP**
  - **\$LINK\_CNL\_STATIC\_SMP**

# Compiling and Linking CNL Windows – Command Line

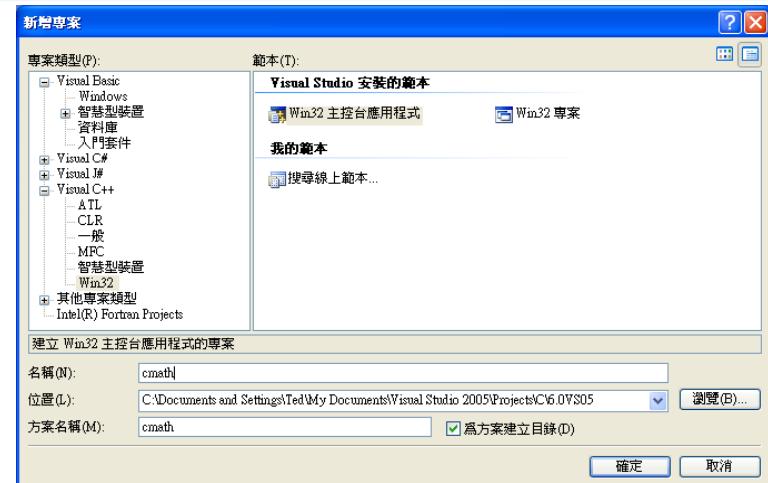


- Link with the DLL libraries version of IMSL CNL
  - CL CMATH.C %LINK\_CNL\_SHARED%
- Link with DLL libraries version of IMSL CNL and links with the supported vendor BLAS and LAPACK
  - CL CMATH.C %LINK\_CNL\_SHARED\_SMP%
- Link with the static libraries version of IMSL CNL
  - CL CMATH.C %LINK\_CNL\_STATIC%
- Link with static libraries version of IMSL CNL and links with the supported vendor BLAS and LAPACK
  - CL CMATH.C %LINK\_CNL\_STATIC\_SMP%

# Compiling and Linking CNL Windows – Visual Studio 2005



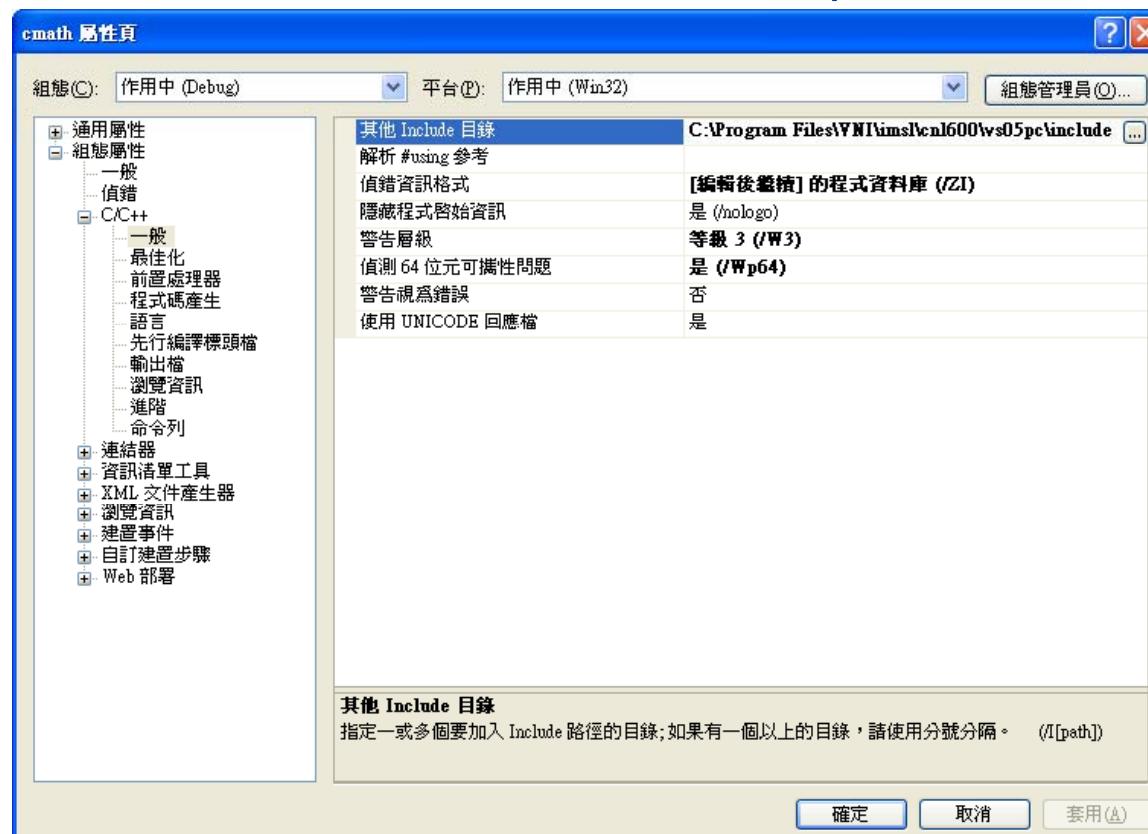
- 檔案 > 新增 > 專案
- Visual C++ > Win32 > Win32 主控台應用程式
- 應用程式設定 > 空專案
- 專案 > 加入現有項目 > C:\Program Files\VNI\imsl\cnl600\vs05pc\examples\validate\cmath.c



# Compiling and Linking CNL Windows – Visual Studio 2005



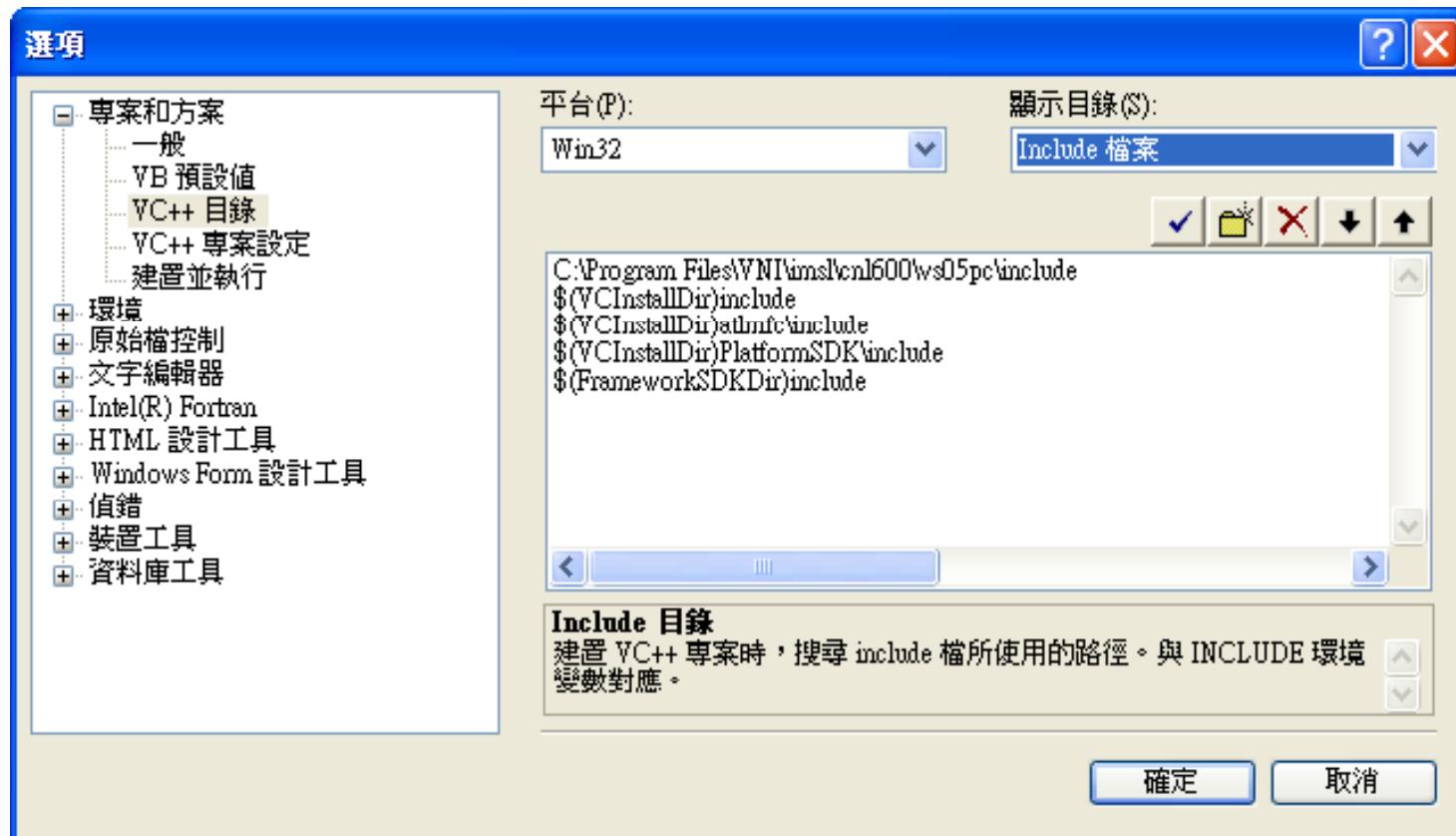
- 專案 > 屬性 > 組態屬性 > C/C++ > 一般 > 其他 Include 目錄 > C:\Program Files\VNI\imsl\cnl600\vs05pc\include



# Compiling and Linking CNL Windows – Visual Studio 2005



- 工具 > 選項 > 專案和方案 > VC++ 目錄 > Include 檔案

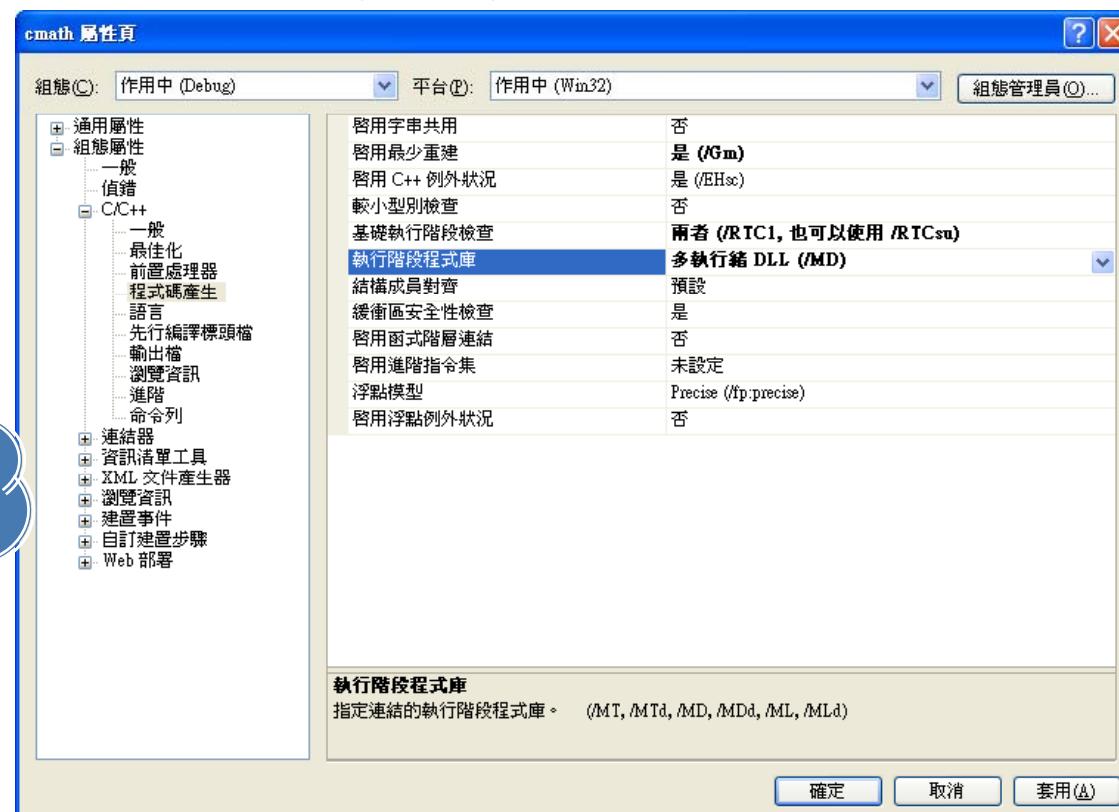


# Compiling and Linking CNL Windows – Visual Studio 2005



- 專案 > 屬性 > 組態屬性 > C/C++ > 程式碼產生 > 執行階段程式庫 > 多執行緒 DLL (/MD)

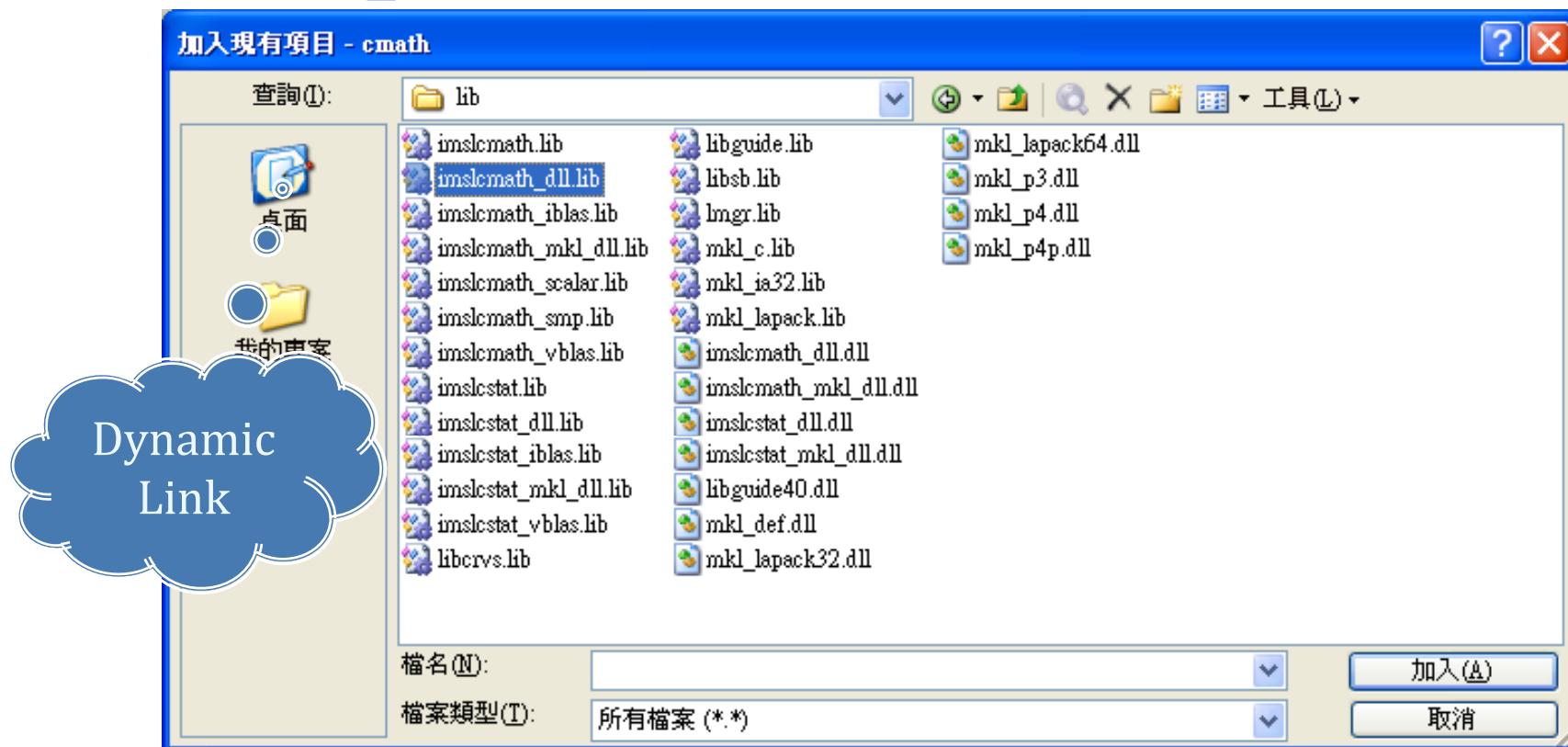
Dynamic Link



# Compiling and Linking CNL Windows – Visual Studio 2005



- 專案 > 加入現有項目 > add imslcmath\_dll.lib (and/or imslcstat\_dll.lib)

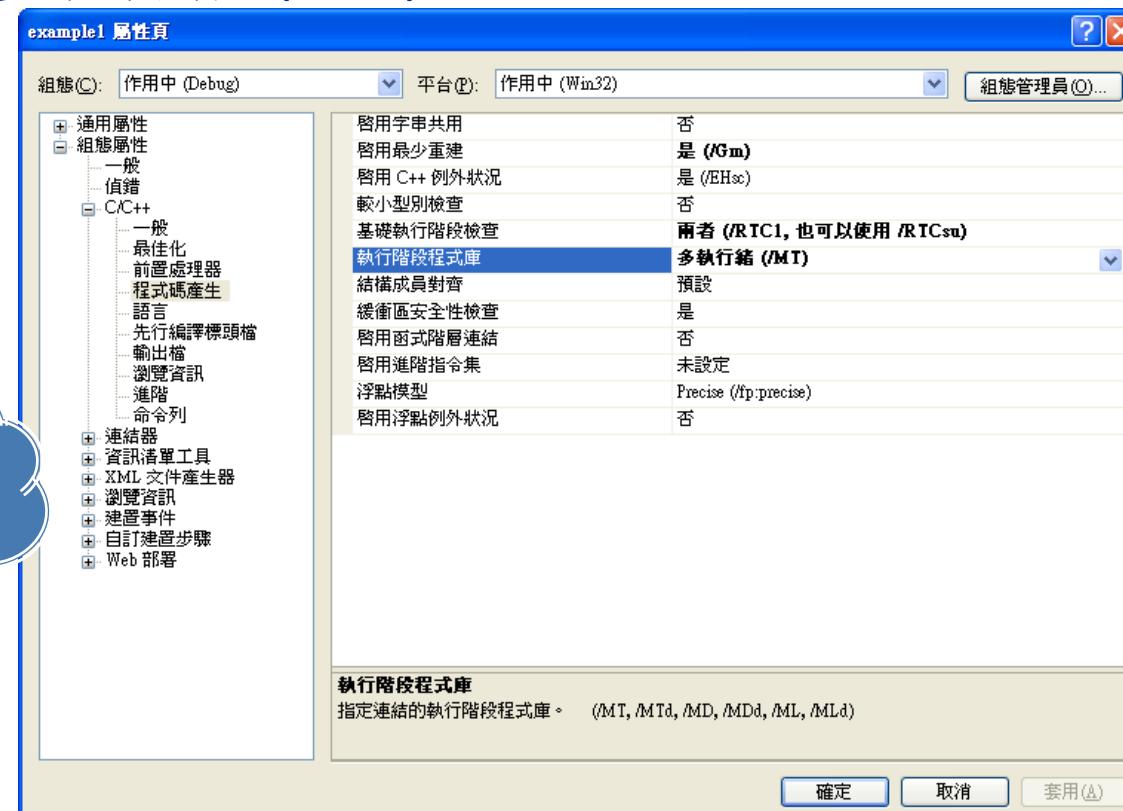


# Compiling and Linking CNL Windows – Visual Studio 2005



- 專案 > 屬性 > 組態屬性 > C/C++ > 程式碼產生 > 執行階段程式庫 > 多執行緒 (/MT)

Static  
Link

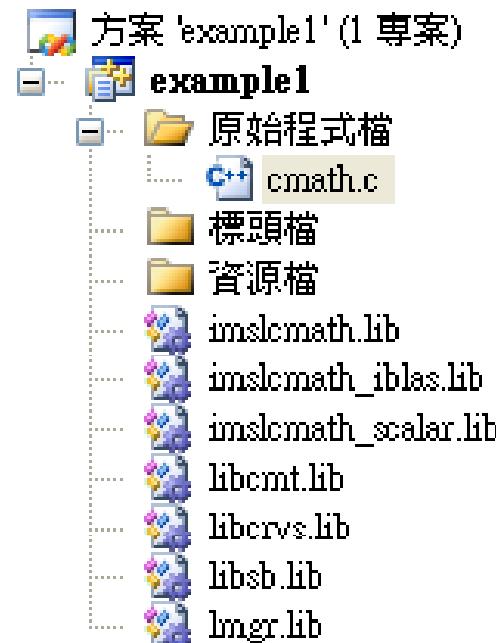


# Compiling and Linking CNL Windows – Visual Studio 2005



- 專案 > 加入現有項目 > imslcmath.lib (and/or imslcstat.lib), imslcmath\_iblas.lib, imslcmath\_scalar.lib, lmgr.lib, libcrvs.lib, Libsb.lib
- 專案 > 加入現有項目 > Program Files\Microsoft Visual Studio 8\VC\lib\libcmt.lib

◦  
◦  
◦

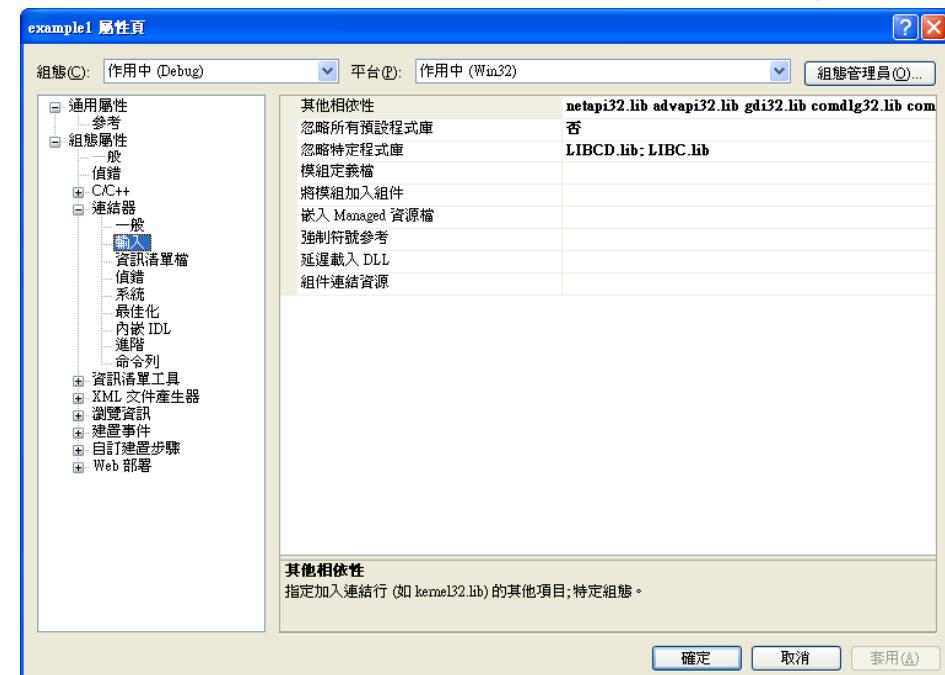


# Compiling and Linking CNL Windows – Visual Studio 2005



- 專案 > 屬性 > 組態屬性 > 連結器 > 輸入 > 其他相依性 > netapi32.lib advapi32.lib gdi32.lib comdlg32.lib comctl32.lib wsock32.lib
- 專案 > 屬性 > 組態屬性 > 連結器 > 輸入 > 忽略特定程式庫 LIBCD.lib; LIBC.lib

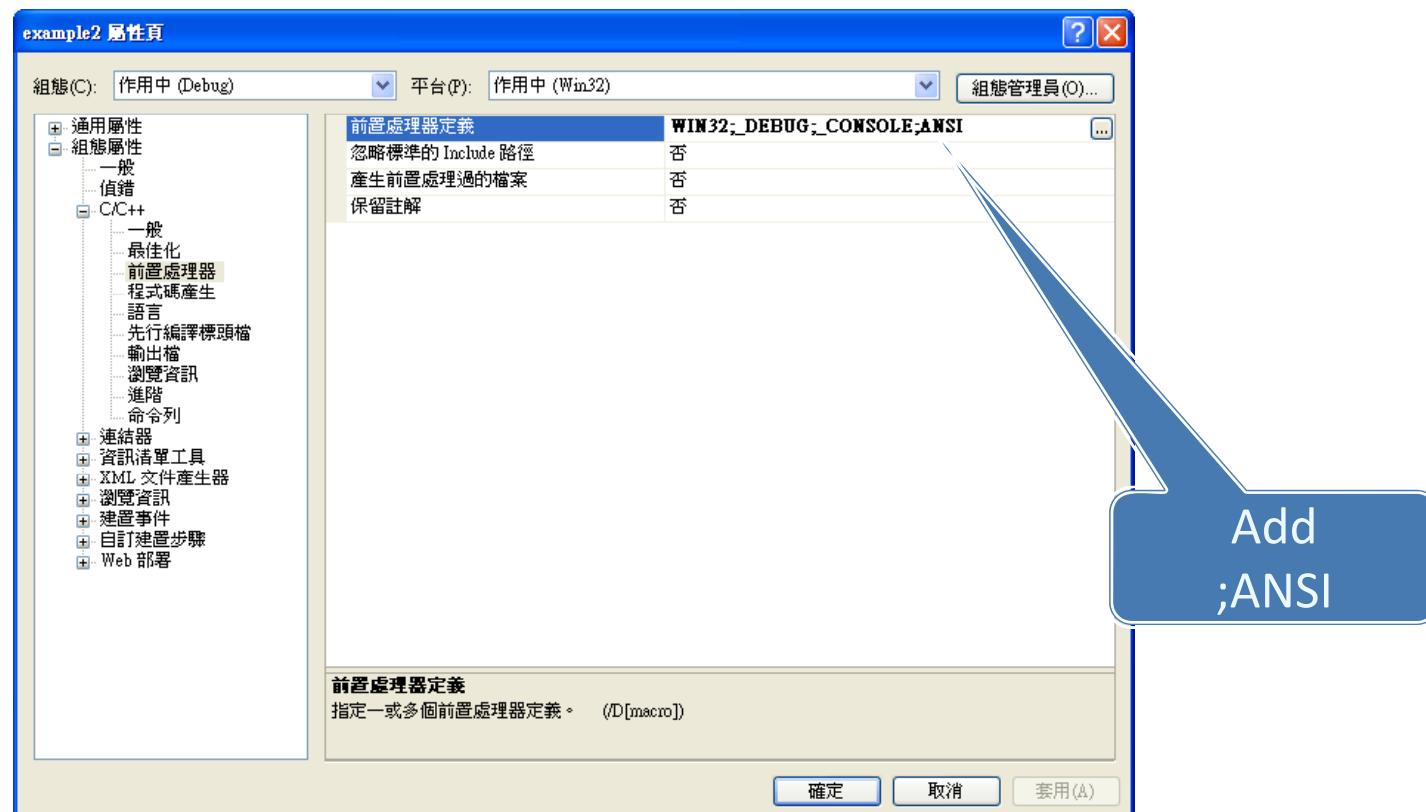
Static  
Link



# Notice IMSL CNL on Windows



- 專案 > 屬性 > 組態屬性 > C/C++ > 前置處理器產生 > 前置處理器定義 > ;ANSI



# Notice IMSL CNL on Windows



```
#include <imsls.h>

void main() {
    int *r;
    int seed = 123457;
    float theta = 0.5;
    imsls_random_seed_set (seed);
    r = imsls_random_poisson (5, theta, 0);
    imsls_i_write_matrix ("Poisson(0.5) random deviates", 1, 5, r, 0);
}
```

## NO Add ANSI Switch

\*\*\* TERMINAL Error from imsls\_random\_poisson. Illegal optional argument  
\*\*\* 1071644672 on argument number 3.

## Add ANSI

Poisson(0.5) random deviates

|   |   |   |   |   |
|---|---|---|---|---|
| 1 | 2 | 3 | 4 | 5 |
| 2 | 0 | 1 | 0 | 1 |

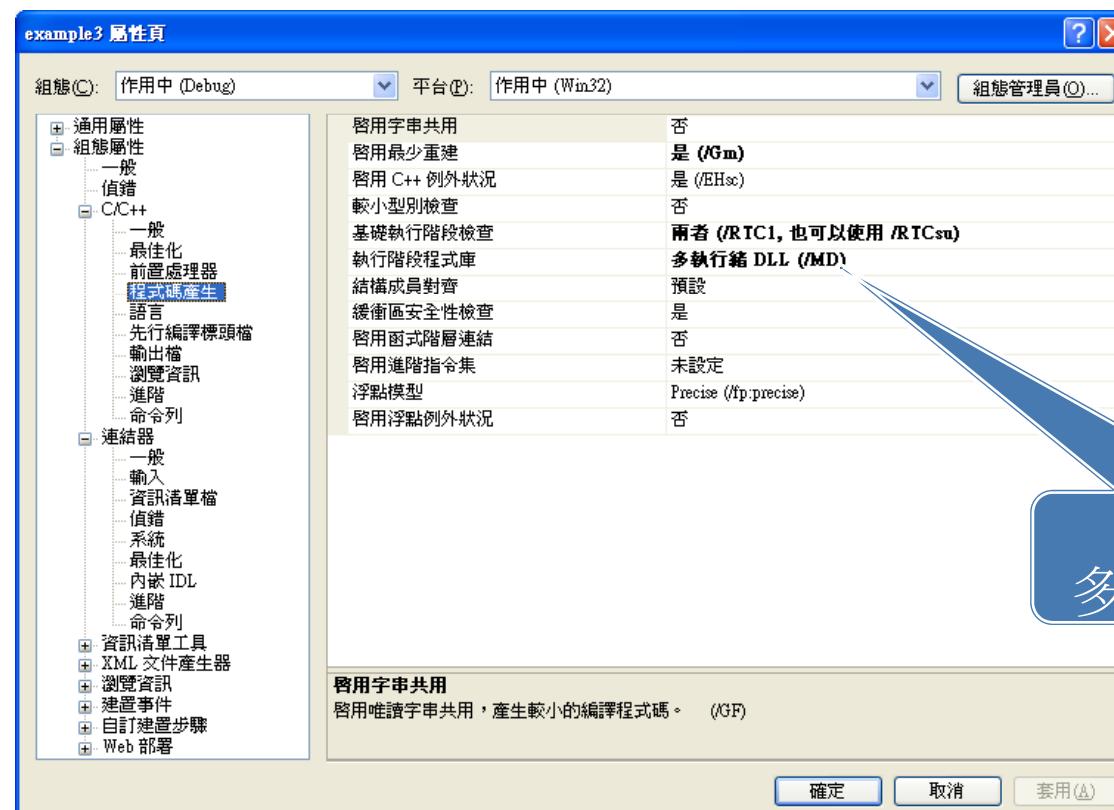


# Notice IMSL CNL on Windows

Windows Only



- 專案 > 屬性 > 組態屬性 > C/C++ > 程式碼產生 > 執行階段程式庫 > 多執行緒 DLL (/MD)



# Notice IMSL CNL on Windows



```
#include <stdio.h>
#include <imsl.h>
main() {
    FILE *ofile;
    float x[] = {3.0, 2.0, 1.0};
    imsl_f_write_matrix ("x (default file)", 1, 3, x, 0);
    ofile = fopen("myfile", "w");
    imsl_output_file (IMSL_SET_OUTPUT_FILE, ofile,0);
    imsl_f_write_matrix ("x (myfile)", 1, 3, x, 0);
}
```

**Using Default**

FATAL ERROR

**Add /MD**

x (default file)

1  
3

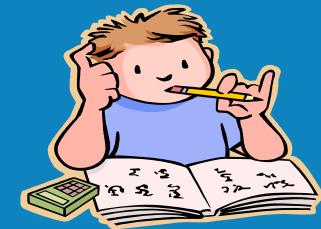
2  
2

3  
1



# IMSL C Exercise 1

## Validate Program



To link and run the validate program

```
cp /opt/vni/imsl/cnl600/itanium/examples/validate0/validate/cmath.c ~/exercise  
$CC $CFLAGS -o cmath cmath.c $LINK_CNL
```

```
./cmath
```

```
Library version: IMSL C/Math/Library Version 6.0
```

```
Solution, x of Ax = b
```

|    |    |   |
|----|----|---|
| 1  | 2  | 3 |
| -2 | -2 | 3 |

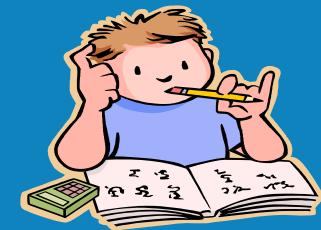
The next call will generate an error

```
*** TERMINAL Error from imsl_f_lin_sol_gen. The order of the matrix must be  
*** positive while "n" = -10 is given.
```



# IMSL C Exercise 2

## Using Optional Arguments



- Solves the transpose problem  $A^T x = b$  and return the LU factorization of A with partial pivoting

$$\begin{aligned}x_1 + 3x_2 + 3x_3 &= 1 \\x_1 + 3x_2 + 4x_3 &= 4 \\x_1 + 4x_2 + 3x_3 &= -1\end{aligned}$$

```
#include <imsl.h>
main()
{
int n = 3, pvt[3];
float factor[9];
float x[3];
float a[] = { 1.0, 3.0, 3.0,
              1.0, 3.0, 4.0,
              1.0, 4.0, 3.0};
float b[] = {1.0, 4.0, -1.0};

    
```

```
imsl_f_lin_sol_gen (n, a, b, IMSL_TRANSPOSE, IMSL_RETURN_USER, x, IMSL_FACTOR_USER, pvt, factor, 0);
imsl_f_write_matrix ("Solution, x, of trans(A)x = b", 1, n, x, 0);
imsl_f_write_matrix ("LU factors of A", n, n, factor, 0);
imsl_i_write_matrix ("Pivot sequence", 1, n, pvt, 0);
}
```

User-allocated containing solution

Solve  $A^T x = b$

Pivot sequence for the factorization

LU factorization of A



# IMSL C Exercise 2

## Submit Job

```
#!/bin/sh
#@ job_type=serial
#@ environment = COPY_ALL
#@ initialdir = /home/tedliu/exercise_c
#@ output = poe1.$(jobid).$(stepid).out
#@ error = poe1.$(jobid).$(stepid).err
#@ wall_clock_limit = 60
#@ class = short
#@ queue
timex ./ex2
sleep 20
```

Solution,  $x$ , of  $\text{trans}(A)x = b$

|   |    |   |
|---|----|---|
| 1 | 2  | 3 |
| 4 | -4 | 1 |

LU factors of  $A$

|   |    |   |   |
|---|----|---|---|
|   | 1  | 2 | 3 |
| 1 | 1  | 3 | 3 |
| 2 | -1 | 1 | 0 |
| 3 | -1 | 0 | 1 |

Pivot sequence

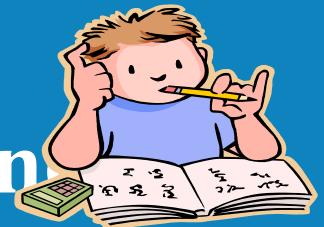
|   |   |   |
|---|---|---|
| 1 | 2 | 3 |
| 1 | 3 | 3 |

llsubmit run2.cmd



# IMSL C Exercise 3

## Call Double Precision Routine



- Solves same problem with double data type

$$\begin{aligned}x_1 + 3x_2 + 3x_3 &= 1 \\x_1 + 3x_2 + 4x_3 &= 4 \\x_1 + 4x_2 + 3x_3 &= -1\end{aligned}$$

```
#include <imsl.h>
main()
{
int n = 3, pvt[3];
double factor[9];
double x[3];
double a[] = { 1.0, 3.0, 3.0,
              1.0, 3.0, 4.0,
              1.0, 4.0, 3.0};
double b[] = {1.0, 4.0, -1.0};

imsl_d_lin_sol_gen (n, a, b, IMSL_TRANSPOSE, IMSL_RETURN_USER, x, IMSL_FACTOR_USER, pvt, factor, 0);
imsl_d_write_matrix ("Solution, x, of trans(A)x = b", 1, n, x, 0);
imsl_d_write_matrix ("LU factors of A", n, n, factor, 0);
imsl_i_write_matrix ("Pivot sequence", 1, n, pvt, 0);
}
```

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# IMSL CNL Inside

# IMSL CNL Error Handling Mechanism

- IMSL CNL functions attempt to detect and report errors and invalid input
- Errors are classified according to severity and are assigned a code number

# IMSL CNL Error Handling Error Type and Actions

- IMSL CNL error type and default actions
  - defined in the include file imsl.h and imsIs.h

| Error Level            | Message PRINT | Program Termination | Contents of ERROR                           |
|------------------------|---------------|---------------------|---|
| IMSL_NOTE              | N             | N                   | Possibility of error                        |
| IMSL_ALERT             | N             | N                   | Underflow                                   |
| IMSL_WARNING           | Y             | N                   | Program must be modified in case            |
| IMSL_FATAL             | Y             | Y                   | Program to be modified                      |
| IMSL_TERMINAL          | Y             | Y                   | Fatal error                                 |
| IMSL_WARNING_IMMEDIATE | Y             | N                   | Same as WARNING<br>Message output is prompt |
| IMSL_FATAL_IMMEDIATE   | Y             | Y                   | Same as FATAL<br>Message output is prompt   |

# IMSL CNL Error Handling error\_options Routines 1/2

- **error\_options**
  - Sets various error handling options
- **Synopsis with Optional Arguments**

```
#include <imsl.h>
void imsl_error_options (
    IMSL_SET_PRINT, Imsl_error type, int setting,
    IMSL_SET_STOP, Imsl_error type, int setting,
    IMSL_SET_TRACEBACK, Imsl_error type, int setting,
    IMSL_FULL_TRACEBACK, int setting,
    IMSL_GET_PRINT, Imsl_error type, int *psetting,
    IMSL_GET_STOP, Imsl_error type, int *psetting,
    IMSL_GET_TRACEBACK, Imsl_error type, int *psetting,
    IMSL_SET_ERROR_FILE, FILE *file,
    IMSL_GET_ERROR_FILE, FILE **pfile,
    IMSL_ERROR_MSG_PATH, char *path,
    IMSL_ERROR_MSG_NAME, char *name
    IMSL_ERROR_PRINT_PROC, Imsl_error_print_proc print_proc,
    IMSL_SET_SIGNAL_TRAPPING, int setting,
    0)
```



# IMSL CNL Error Handling error\_options Routines 2/2

- **imsl\_error\_options** (IMSL\_SET\_PRINT, lmsl\_error type, int setting, 0);

- 0 (zero for all types)
- IMSL\_NOTE
- IMSL\_ALERT
- IMSL\_WARNING
- IMSL\_WARNING\_IMMEDIATE
- IMSL\_FATAL
- IMSL\_FATAL\_IMMEDIATE
- IMSL\_TERMINAL

- -1: no change
- 1: output
- 0: no output
- 2: back to default

- Example
  - Continue at FATAL level and print message at ALERT
  - **imsl\_error\_options (IMSL\_SET\_STOP, IMSL\_FATAL, 0, IMSL\_SET\_PRINT, IMSL\_ALERT, 1, 0);**

# IMSL CNL Error Handling error\_code Routines

- **error\_code**
  - Gets the code corresponding to the error message from the last function called
- **Synopsis**
  - `#include <imsl.h>`
  - `long imsl_error_code ()`
- **Return Value**
  - This function returns the error message code from the last IMSL function called

- The include file imsl.h and imsIs.h defines a name for each error code

- Example

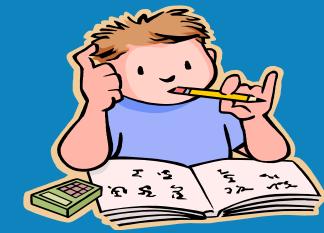
```
x = imsl_f_lin_sol_gen (n, a, b, 0);
If (imsl_error_code() == IMSL_SINGULAR_MATRIX) {
    process at error
}
```

lin\_sol\_gen defines  
FATAL Error: The input matrix is singular



# IMSL C Exercise 4

## IMSL Error Handling



```
#include <stdio.h>
#include "imsl.h"
int main (int argc, char* argv[]) {
    float res;
    long code;

    imsl_error_options (IMSL_SET_STOP, IMSL_TERMINAL, 0, 0);
    res = imsl_f_beta (-1.0, .5);
    code = imsl_error_code ();
    printf ("Error Code = %d\n", code);
    printf ("Run to here....\n\n");
}
```

Evaluates the complete beta function  
***float imsl\_f\_beta (float a, float b)***

\*\*\* TERMINAL Error from imsl\_f\_beta. Both "x" = -1.000000e+00 and "y" =  
 \*\*\* 5.000000e-01 must be greater than zero.



Without error\_options code

\*\*\* TERMINAL Error from imsl\_f\_beta. Both "x" = -1.000000e+00 and "y" =  
 \*\*\* 5.000000e-01 must be greater than zero.



With error\_options code

Error Code = 9031  
 Run to here....



# IMSL CNL Error Handling

## Customize Error Message

- Error messages file and utilities located at
  - /usr/local/imsl/cnl600/rs6000\_64/bin
    - Error messages raw data
      - imslerr.dat / imsls\_e.dat
    - Error utility
      - imslerr and imsls\_e
    - Error message file
      - imslerr.bin / imsls\_e.bin
    - Environment variable
      - IMSLERRPATH
      - IMSLSERRPATH

:  
9030 IMSL\_ERF\_ALGORITHM Sufficiently accurate result was not & achieved. An algorithmic problem & exists.  
9031 IMSL\_BETA\_NEG\_ARG Both "x" = %(F1) and "y" = %(F2) must be & greater than zero. :  
:

# IMSL Underflow and Overflow

- Underflow
  - IMSL codes are written so that computations are not affected by underflow
  - System places a zero in the register
  - Error level is **IMSL\_ALERT**
- Overflow
  - IMSL codes are written to avoid overflow
  - A program that produces system error message indicating overflow should be examined for programming errors
  - Error level is **IMSL\_FATAL**
  - Example of error code
    - IMSL\_LARGE\_ARG\_OVERFLOW
    - IMSL\_ZERO\_ARG\_OVERFLOW
    - IMSL\_SMALL\_ARG\_OVERFLOW

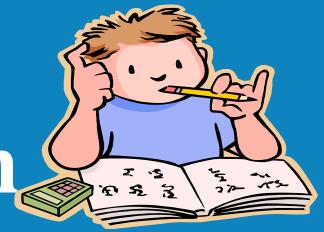
# Missing Values

- Some functions in the IMSL CNL allow the data to contain missing values
- These functions recognize as a missing value the special value referred to as “Not a Number” or NaN
- The actual missing value is different on different computers
  - It can be obtained by reference to the function **machine**



# IMSL C Exercise 5

## Get Computer's Information



```
#include <imsl.h>
main() {
    int n;
    float fans;
    double dans;
    for (n = 1; n <= 8; n++) {
        fans = imsl_f_machine (n);
        printf("imsl_f_machine(%d) = %g\n", n, fans);
    }
    for (n = 1; n <= 8; n++) {
        dans = imsl_d_machine (n);
        printf("imsl_d_machine(%d) = %g\n", n, dans);
    }
}
```

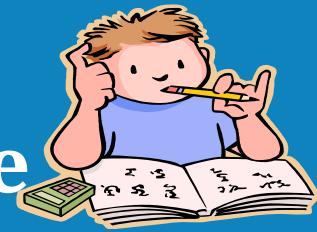
| n | Definition  |
|---|---|
| 1 | $B^{E_{\min_f}-1}$ , the smallest positive number |
| 2 | $B^{E_{\max_f}}(1-B^{-N_f})$ , the largest number |
| 3 | $B^{-N_f}$ , the smallest relative spacing        |
| 4 | $B^{1-N_f}$ , the largest relative spacing        |
| 5 | $\log_{10}(B)$                                    |
| 6 | NaN (not a number)                                |
| 7 | positive machine infinity                         |
| 8 | negative machine infinity                         |

|                                  |
|----------------------------------|
| imsl_f_machine(1) = 1.17549e-38  |
| imsl_f_machine(2) = 3.40282e+38  |
| imsl_f_machine(3) = 5.96046e-08  |
| imsl_f_machine(4) = 1.19209e-07  |
| imsl_f_machine(5) = 0.30103      |
| imsl_f_machine(6) = NaNQ         |
| imsl_f_machine(7) = INF          |
| imsl_f_machine(8) = -INF         |
|                                  |
| imsl_d_machine(1) = 2.22507e-308 |
| imsl_d_machine(2) = 1.79769e+308 |
| imsl_d_machine(3) = 1.11022e-16  |
| imsl_d_machine(4) = 2.22045e-16  |
| imsl_d_machine(5) = 0.30103      |
| imsl_d_machine(6) = NaNQ         |
| imsl_d_machine(7) = INF          |
| imsl_d_machine(8) = -INF         |



# IMSL C Exercise 6

## Data Contains Missing Value



```
#include <imsls.h>
#define N_OBSERVATIONS 10
#define N_VARIABLES 3
main() {
    int n_keys=2;
    float x[N_OBSERVATIONS][N_VARIABLES] = {
        1.0, 1.0, 1.0,
        2.0, 1.0, 2.0,
        1.0, 1.0, 3.0,
        1.0, 1.0, 4.0,
        2.0, 2.0, 5.0,
        1.0, 2.0, 6.0,
        1.0, 2.0, 7.0,
        1.0, 1.0, 8.0,
        2.0, 2.0, 9.0,
        1.0, 1.0, 9.0};
    x[4][1]=imsls_f_machine(6);
    x[6][0]=imsls_f_machine(6);
    imsls_f_sort_data (N_OBSERVATIONS, N_VARIABLES, x, n_keys, 0);
    imsls_f_write_matrix("sorted x", N_OBSERVATIONS, N_VARIABLES, (float *)x, 0);
}
```

### sort\_data

Sorts observations by specified keys, with option to tally cases into a multi-way frequency table.

#### Synopsis

```
#include <imsls.h>
void imsls_f_sort_data (int n_observations, int n_variables, float x[], int n_keys, ..., 0)
```

- **int n\_observations** (Input) Number of observations (rows) in x.
- **int n\_variables** (Input) Number of variables (columns) in x.
- **float x[]** (Input/Output) An n\_observations x n\_variables matrix containing the observations to be sorted. The sorted matrix is returned in x
- **int n\_keys** (Input) Number of columns of x on which to sort. The first n\_keys columns of x are used as the sorting keys

sorted x

|    |       |       |   |
|----|-------|-------|---|
|    | 1     | 2     | 3 |
| 1  | 1     | 1     | 1 |
| 2  | 1     | 1     | 9 |
| 3  | 1     | 1     | 3 |
| 4  | 1     | 1     | 4 |
| 5  | 1     | 1     | 8 |
| 6  | 1     | 2     | 6 |
| 7  | 2     | 1     | 2 |
| 8  | 2     | 2     | 9 |
| 9  | ..... | 2     | 7 |
| 10 | 2     | ..... | 5 |



# IMSL CNL Thread Safe Usage Overview

- IMSL CNL can be safely called from a multithreaded application
  - Support either **POSIX** threads or **WIN32** threads
- IMSL CNL is used in a multithreaded application, the calling program must adhere
  1. Signal handling
  2. Routines that Produce Output
  3. Input Arguments



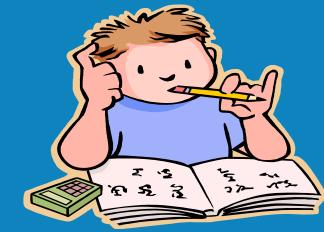
# IMSL CNL Thread Safe Usage Signal Handling

- When calling IMSL CNL from a multithreaded application it is necessary to **turn** IMSL signal-handling capability **off**
- The IMSL signal-trapping mechanism must be disabled before any threads are created
  - **imsl\_error\_options (IMSL\_SET\_SIGNAL\_TRAPPING, 0, 0);**



# IMSL C Exercise 7

## Turn Off Signal-Trapping



IMSL signal-trapping mechanism must be disabled before any threads are created

```
#include <pthread.h>
#include <stdio.h>
#include "imsl.h"
void *ex1(void* arg);
void *ex2(void* arg);
void main() {
    pthread_t thread1;
    pthread_t thread2;

    imsl_error_options (IMSL_SET_SIGNAL_TRAPPING, 0, 0);

    pthread_create(&thread1, NULL ,ex1, (void *)NULL);
    pthread_create(&thread2, NULL ,ex2, (void *)NULL);
    pthread_join(thread1, NULL);
    pthread_join(thread2, NULL);
}
```

```
void *ex1(void *arg) {
    float res;
    res = imsl_f_beta (0.5, 0.2);
    printf("Thread 1 %f \n", res);
}

void *ex2(void *arg) {
    float res;
    res = imsl_f_gamma (1.5);
    printf("Thread 2 %f \n", res);
}
```

Thread 2 0.886227  
Thread 1 6.268653

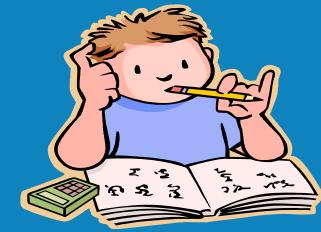
Without SIGNAL TRAPPING

```
*** FATAL Error IMSL_NO_MT_SIGNAL_HANDLING from imsl_f_beta.
*** C/Math/Library signal handling must be turned off when using
*** multiple threads. See imsl_err_options for instructions on
*** turning off signal handling by C/Math/Library.
:
```



# IMSL C Exercise 8

## Set Thread's Error Handler



Each thread can set its own options for IMSL CNL error handler

```
#include <pthread.h>
#include <stdio.h>
#include "imsl.h"
void *ex1(void* arg);
void *ex2(void* arg);
void main() {
    pthread_t thread1;
    pthread_t thread2;

    imsl_error_options (IMSL_SET_SIGNAL_TRAPPING, 0, 0);

    if (pthread_create(&thread1, NULL ,ex1, (void *)NULL) != 0)
        perror("pthread_create"), exit(1);
    if (pthread_create(&thread2, NULL ,ex2, (void *)NULL) != 0)
        perror("pthread_create"), exit(1);

    if (pthread_join(thread1, NULL) != 0)
        perror("pthread_join"),exit(1);
    if (pthread_join(thread2, NULL) != 0)
        perror("pthread_join"),exit(1);
}
```

```
void *ex1(void* arg) {
    float res;
    imsl_error_options (IMSL_SET_STOP, IMSL_TERMINAL, 0, 0);
    res = imsl_f_beta(-1.0, .5);
}

void *ex2(void* arg) {
    float res;
    imsl_error_options (IMSL_SET_STOP, IMSL_TERMINAL, 0,
                        IMSL_SET_TRACEBACK, IMSL_TERMINAL, 1, 0);
    res = imsl_f_gamma(-1.0);
}
```

\*\*\* TERMINAL Error from imsl\_f\_beta. Both "x" = -1.000000e+00 and "y" = 5.000000e-01 must be greater than zero.

\*\*\* TERMINAL Error from imsl\_f\_gamma. The argument for the function can not be a negative integer. Argument "x" = -1.000000e+00.

Here is a traceback of the calls in reverse order.

| Error Type    | Error Code            | Routine              |
|---------------|-----------------------|----------------------|
| IMSL_TERMINAL | IMSL_NEGATIVE_INTEGER | imsl_f_gamma<br>USER |



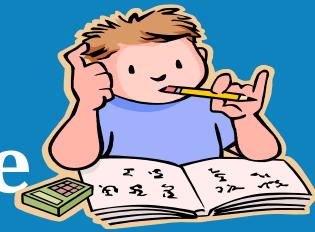
# IMSL CNL Thread Safe Usage Produce Output

- The function **imsl\_output\_file** can be used to control which file the output is directed
- Each thread must call **imsl\_output\_file** to change the default setting of where output will be directed



# IMSL C Exercise 9

## Change Thread's Output File



Each thread must call `imsl_output_file` to change the default setting of where output will be directed

```
#include <pthread.h>
#include <stdio.h>
#include "imsl.h"
void *ex1(void* arg);
void *ex2(void* arg);
void main() {
    pthread_t thread1;
    pthread_t thread2;
    imsl_error_options(IMSL_SET_SIGNAL_TRAPPING, 0, 0);
    pthread_create(&thread1, NULL, ex1, (void *)NULL);
    pthread_create(&thread2, NULL, ex2, (void *)NULL);
    pthread_join(thread1, NULL);
    pthread_join(thread2, NULL);
}

void *ex1(void* arg) {
    float *rand_nums = NULL;
    FILE *file_ptr;
    file_ptr = fopen("thread1.out", "w");
    imsl_output_file (IMSL_SET_OUTPUT_FILE, file_ptr, 0);
}
```

```
imsl_random_seed_set(12345);
rand_nums = imsl_f_random_uniform (5, 0);
imsl_f_write_matrix ("Random Numbers", 5, 1, rand_nums, 0);
fclose(file_ptr);

}
void *ex2(void* arg) {
    int n = 3;
    float *x;
    float a[] = {1.0, 3.0, 3.0,
                 1.0, 3.0, 4.0,
                 1.0, 4.0, 3.0};
    float b[] = {1.0, 4.0, -1.0};
    FILE *file_ptr;

    file_ptr = fopen ("thread2.out", "w");
    imsl_output_file (IMSL_SET_OUTPUT_FILE, file_ptr, 0);
    x = imsl_f_lin_sol_gen (n, a, b, 0);
    imsl_f_write_matrix ("Solution, x, of Ax = b", 1, 3, x, 0);
    fclose(file_ptr);
}
```

```
>cat thread1.out
Random Numbers
1      0.0966
2      0.8340
3      0.9477
4      0.0359
5      0.0115
```

```
>cat thread2.out
```

Solution, x, of Ax = b

|    |    |   |
|----|----|---|
| 1  | 2  | 3 |
| -2 | -2 | 3 |

# IMSL CNL Thread Safe Usage Input Arguments

- Some arguments that may appear to be input-only are temporarily modified during the call and restored before returning to the caller
- **Avoid** usage of the same data space in separate threads calling functions in IMSL CNL

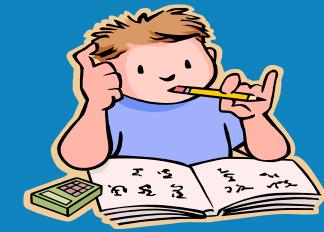
# Memory Allocation for Output 1/2

- Many functions return a pointer to an array
- **IMSL\_RETURN\_USER**, float a[]
  - The answers are stored in the user-provided array, and the pointer returned by the function is set to point to the user-provided array
  - If an invocation **does not** use **IMSL\_RETURN\_USER**, then the function initializes the pointer (through a memory allocation request to *malloc*) and stores the answers there



# IMSL C Exercise 10

## IMSL Routine's Answer



```
#include <imsl.h>
main() {
    int n = 3;
    float x1[3];
    float *x2;
    float a[] = { 1.0, 3.0, 3.0,
                  1.0, 3.0, 4.0,
                  1.0, 4.0, 3.0};
    float b[] = {1.0, 4.0, -1.0};

    imsl_f_lin_sol_gen (n, a, b, IMSL_RETURN_USER, x1, 0);
    x2 = imsl_f_lin_sol_gen (n, a, b, 0);

    imsl_f_write_matrix ("Solution 1", 1, n, x1, 0);
    imsl_f_write_matrix ("Solution 2", 1, n, x2, 0);
}
```

| Solution 1 |    |   |
|------------|----|---|
| 1          | 2  | 3 |
| -2         | -2 | 3 |
| Solution 2 |    |   |
| 1          | 2  | 3 |
| -2         | -2 | 3 |

User provided array

Initializes a pointer

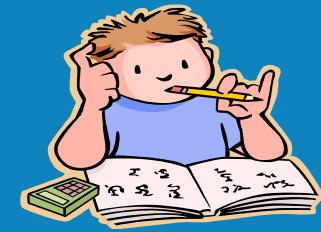
## Memory Allocation for Output 2/2

- Some optional arguments specify whether additional computed output arrays
  - Allocated by the user
  - Allocated internally by the function
- Example
  - lin\_sol\_gen
    - IMSL\_INVERSE\_USER, float inva[]
    - IMSL\_INVERSE, float \*\*p\_inva
  - Allocated by the user
    - float inva[9];
    - imsl\_f\_lin\_sol\_gen (n, a, b, IMSL\_INVERSE\_USER, inva, ... );
  - Allocated internally by the function
    - float \*p\_inva;
    - imsl\_f\_lin\_sol\_gen (n, a, b, IMSL\_INVERSE, &p\_inva, ...);



# IMSL C Exercise 11

## Computation Output Array



```
#include <imsl.h>
main() {
    int n = 3;
    float *x;
    float a[] = { 1.0, 3.0, 3.0,
                  1.0, 3.0, 4.0,
                  1.0, 4.0, 3.0};
    float b[] = {1.0, 4.0, -1.0};

    float *inva1;
    float inva2[9];

    x = imsl_f_lin_sol_gen (n, a, b, IMSL_INVERSE, &inva1, 0);
    x = imsl_f_lin_sol_gen (n, a, b, IMSL_INVERSE_USER, inva2, 0);

    imsl_f_write_matrix ("Solution 1", n, n, inva1, 0);
    imsl_f_write_matrix ("Solution 2", n, n, inva2, 0);
}
```

**IMSL\_INVERSE**  
inverse of the matrix A

| Solution 1 |    |    |    |
|------------|----|----|----|
| 1          | 2  | 3  | 3  |
| 1          | 7  | -3 | -3 |
| 2          | -1 | 0  | 1  |
| 3          | -1 | 1  | 0  |

| Solution 2 |    |    |    |
|------------|----|----|----|
| 1          | 2  | 3  | 3  |
| 1          | 7  | -3 | -3 |
| 2          | -1 | 0  | 1  |
| 3          | -1 | 1  | 0  |

Initializes a pointer

User provided array

# Printing Results

- Most IMSL CNL functions do not print any of the results, the output is returned in C variables

- **write\_matrix**

- Prints a rectangular matrix (or vector) stored in contiguous memory locations

- **Synopsis**

```
#include <imsl.h>
void imsl_f_write_matrix (char *title, int nra, int nca, float a[], ..., 0)
For int a[], use imsl_i_write_matrix
For double a[], use imsl_d_write_matrix
For f_complex a[], use imsl_c_write_matrix
For d_complex a[], use imsl_z_write_matrix
```

- **Required Arguments**

char \*title (Input)

The matrix title. Use \n within a title to create a new line. Long titles are automatically wrapped

int nra (Input)

The number of rows in the matrix

int nca (Input)

The number of columns in the matrix

float a[] (Input)

Array of size nra x nca containing the matrix to be printed



# IMSL CNL

## Complex Data Types

- Users can perform computations with complex arithmetic by using IMSL predefined data types

- `f_complex`
  - `d_complex`

- The structure is declared as

```
typedef struct {  
    float re;  
    float im;  
} f_complex;
```



# IMSL CNL Complex Functions

| Operation                | Function Name                         | Result                 |
|--------------------------|---------------------------------------|------------------------|
| $z = x + y$              | <code>z = imsl_c_add(x,y)</code>      | <code>f_complex</code> |
| $z = x$ (drop precision) | <code>z = imsl_cz_convert(x)</code>   | <code>f_complex</code> |
| $z = a + ib$             | <code>z = imsl_cf_convert(a,b)</code> | <code>f_complex</code> |
| $a =  z $                | <code>a = imsl_c_abs(z)</code>        | <code>float</code>     |
| $z = \cos(x)$            | <code>z = imsl_c_cos(z)</code>        | <code>f_complex</code> |
| $z = x^a$                | <code>z = imsl_cf_power(x,a)</code>   | <code>f_complex</code> |
| :                        | :                                     | :                      |

# Parallelism in the IMSL CNL

- IMSL CNL employs fine-grain parallelism to take advantage of multiple CPUs
- Fine-grain parallelism
  - Within a subroutine or function and is limited to shared-memory (SMP)
  - Done at the DO loop level
- Parallelism is seamless to the user
  - Only the environment variables need to be set and used



# IMSL CNL 6.0

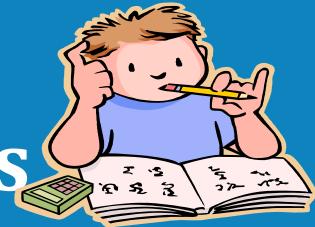
## Performance Enhancements 1/2

- Performance increases can be realized by taking advantage of vendor supplied BLAS, FFT and LAPACK routines (**IBM ESSL 4.2**)
  - `LINK_CNL_SHARED_SMP`
    - link with the shared library
  - `LINK_CNL_STATIC_SMP`
    - link with the static library
- IMSL CNL also uses IBM ESSL library to take advantage of multiple CPUs
  - Set **OMP\_NUM\_THREADS**=<number of threads to use>
  - Default is 1



# IMSL C Exercise 12

## Performance Enhancements



```
#include <imsl.h>
#include <stdio.h>
#define N 3000
void main() {
    float *x;
    float *a, *b;
    clock_t start, finish;

    a = imsl_f_random_uniform (N*N, 0);
    b = imsl_f_random_uniform (N, 0);

    start = clock();
    x = imsl_f_lin_sol_gen (N, a, b, 0);
    finish = clock();
    printf("Used %.2f seconds.\n",
        (double)(finish - start)/CLOCKS_PER_SEC);
}
```

N = 3000

```
$CC -o ex12 ex12.c $CFLAGS $LINK_CNL
./ex12
Used 19.88 seconds.
```

```
$CC -o ex12 ex12.c $CFLAGS $LINK_CNL_SMP
./ex12
Used 5.45 seconds.
```

N = 4000

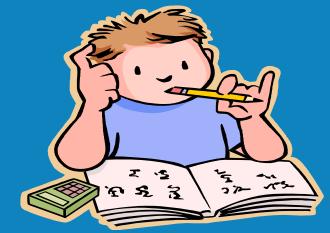
```
$CC -o ex12 ex12.c $CFLAGS $LINK_CNL
./ex12
Used 49.92 seconds.
```

```
$CC -o ex12 ex12.c $CFLAGS $LINK_CNL_SMP
./ex12
Used 12.71 seconds.
```

$$\min \frac{1}{2} \sum_{i=1}^N f_i(x)$$

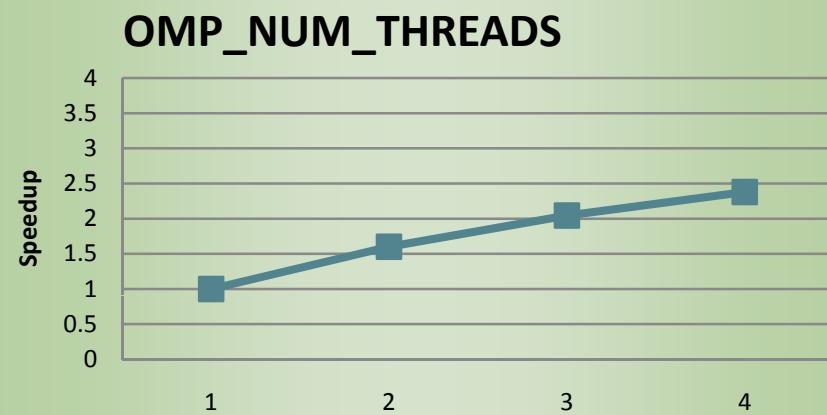
# IMSL C Exercise 13

## IMSL CNL Support SMP



```
#include <imsl.h>
#include <stdio.h>
#define N 5000
void main() {
    float *x;
    float *a, *b;
    a = imsl_f_random_uniform (N*N, 0);
    b = imsl_f_random_uniform (N, 0);

    x = imsl_f_lin_sol_gen (N, a, b, 0);
}
```



```
export OMP_NUM_THREADS=1
timex ./ex13
real 25.80
user 25.72
sys 0.00
```

```
export OMP_NUM_THREADS=2
timex ./ex13
real 16.13
user 26.60
sys 0.10
```

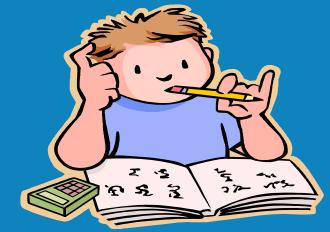
```
export OMP_NUM_THREADS=3
timex ./ex13
real 12.62
user 26.56
sys 0.15
```

```
export OMP_NUM_THREADS=4
timex ./ex13
real 10.84
user 26.59
sys 0.25
```



# IMSL C Exercise 14

## Submit Job for SMP



```
#include <imsl.h>
#include <stdio.h>
#define N 5000
void main() {
    float *x;
    float *a, *b;

    a = imsl_f_random_uniform(N*N, 0);
    b = imsl_f_random_uniform(N, 0);

    x = imsl_f_lin_sol_gen (N, a, b, 0);
}
```

```
#!/bin/sh
#@ job_type=serial
#@ environment = COPY_ALL
#@ initialdir = /home/tedliu/exercise_c
#@ output = poe1.$(jobid).$(stepid).out
#@ error = poe1.$(jobid).$(stepid).err
#@ wall_clock_limit = 60
#@ class = short
#@ environment = OMP_NUM_THREADS=4
#@ queue
timex ./ex14
sleep 20
```

```
llsubmit run14.cmd
llsubmit: The job "i82.2737" has been submitted.
cat poe1.2737.0.err

real 9.37
user 22.80
sys 0.17
```

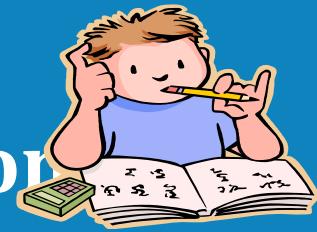
# User-Supplied Function

- Some IMSL CNL routines accept user-supplied function
- Example **min\_uncon**
  - Find the minimum point of a smooth function  $f(x)$  of a single variable using only function evaluations
  - Synopsis
    - float imsl\_f\_min\_uncon (float fcn(), float a, float b, ..., 0)
  - Required Arguments
    - float imsl\_f\_min\_uncon (float fcn(), float a, float b, ..., 0)
    - float fcn(float x)
      - User-supplied function to compute
    - float a
      - The lower endpoint of the interval
    - float b
      - The upper endpoint of the interval



# IMSL C Exercise 15

## Solve User Supplied Equation



Optimization Function : Minimum point of  $f(x) = ex - 5x$

```
#include <imsl.h>
#include <math.h>
float fcn(float);
void main () {
    float a = -100.0;
    float b = 100.0;
    float fx, x;
    x = imsl_f_min_uncon (fcn, a, b, 0);
    fx = fcn(x);
    printf ("The solution is: %8.4f\n", x);
    printf ("The function evaluated at the solution is: %8.4f\n", fx);
}

float fcn(float x) {
    return exp(x) - 5.0*x;
}
```

lower (-100) and upper (100) endpoint  
of the interval

The solution is: 1.6094  
The function evaluated at the solution is: -3.0472

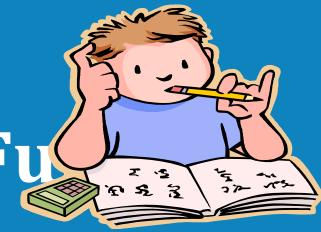
# Passing Data to User-Supplied Function

- User-supplied functions requires data that is local to the user's calling function
- User wants to avoid using global data to allow the user-supplied function to access the data
  - Optional arguments can accept an alternative user-supplied function, along with a pointer to the data
  - **IMSL\_FCN\_W\_DATA, float fcn(float x, void \*data)**



# IMSL C Exercise 16

## Passing Data to User-Supplied Function



Optimization Function : Minimum point of  $f(x) = ex - 5x$

```
#include "imsl.h"
#include <math.h>
static float fcn_w_data(float x, void *data_ptr);
static float fcn(float);
void main() {
    float a = -100.0;
    float b = 100.0;
    float fx, x;
    float usr_data[] = {5.0};
    x = imsl_f_min_uncon (fcn, a, b, IMSL_FCN_W_DATA, fcn_w_data, usr_data, 0);
    fx = fcn_w_data (x, (void*)usr_data);
    printf ("The solution is: %8.4f\n", x);
    printf ("The function evaluated at the solution is: %8.4f\n", fx);
}
```

```
static float fcn_w_data(float x, void *data_ptr) {
    return exp(x) - (*((float*)data_ptr))* x;
}
static float fcn(float x) {
    return;
}
```



# IMSL Quadrature Example - Multivariate Quadrature

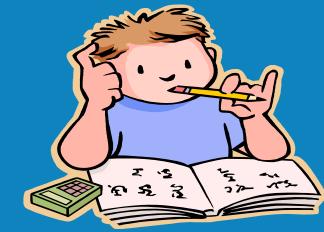
- **int\_fcn\_2d**
  - Computes a two-dimensional iterated integral.
- **Synopsis**
  - float imsl\_f\_int\_fcn\_2d (float fcn(), float a, float b, float gcn (float x), float hcn (float x), ..., 0)
- **Required Arguments**
  - float fcn (float x, float y) (Input)
    - User-supplied function to be integrated
  - float a (Input)
    - Lower limit of outer integral
  - float b (Input)
    - Upper limit of outer integral
  - float gcn (float x) (Input)
    - User-supplied function to evaluate the lower limit of the inner integral
  - float hcn (float x) (Input)
    - User-supplied function to evaluate the upper limit of the inner integral
- **Return Value**
  - The value of

$$\int_a^b \int_{gcn(x)}^{hcn(x)} fcn(x, y) dy dx$$



# IMSL C Exercise 17

## Quadrature Example



Compute the value of the integral

```
#include <math.h>
#include <imsl.h>

float fcn(float x, float y), gcn(float x), hcn(float x);

main() {
    float q, exact;
    q = imsl_f_int_fcn_2d (fcn, 0.0, 1.0, gcn, hcn, 0);
    exact = 0.5*(cos(9.0)+cos(2.0)-cos(10.0)-cos(1.0));
    printf("integral = %10.3f\nexact = %10.3f\n", q, exact);
}

float fcn (float x, float y) {
    return y * cos(x+y*y);
}

float gcn (float x) {
    return 1.0;
}

float hcn (float x) {
    return 3.0;
}
```

Lower (0) and upper (1) limit of outer integral

$$\int_0^1 \int_0^3 y \cos(x + y^2) dy dx$$

integral = -0.514  
exact = -0.514



# IMSL Differential Equations

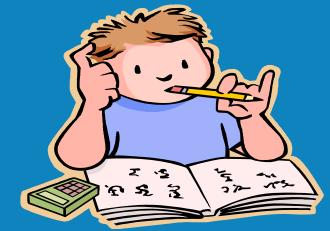
## Example – ODE solution of initial-value

- **ode\_runge\_kutta**
  - Solves an initial-value problem for ordinary differential equations using the Runge-Kutta-Verner
- **Synopsis**
  - float imsl\_f\_ode\_runge\_kutta\_mgr (int task, void \*\*state, ..., 0)
  - void imsl\_f\_ode\_runge\_kutta (int neq, float \*t, float tend, float y[], void \*state, void fcn())
- **Required Arguments for imsl\_f\_ode\_runge\_kutta**
  - int neq (Input)
    - Number of differential equations
  - float \*t (Input/Output)
    - Independent variable. On input, t is the initial independent variable value. On output, t is replaced by tend
  - float tend (Input)
    - Value of t at which the solution is desired
  - float y[] (Input/Output)
    - Array with neq components containing a vector of dependent variables.
  - void \*state (Input/Output)
    - The current state of the ODE solution is held in a structure pointed to by state
  - void fcn (int neq, float t, float \*y, float \*yprime)
    - **User-supplied** function to evaluate the right-hand side



# IMSL C Exercise 18

## ODE Example



This example solves  $\frac{dy}{dx} = -y$  over the interval [0, 1] with the initial condition  $y(0) = 1$ . The solution is  $y(t) = e^{-t}$

```
#include <imsl.h>
#include <math.h>

void fcn (int neq, float t, float y[], float yprime[]);
main() {
    int neq = 1; /* Number of ode's */
    float t = 0.0; /* Initial time */
    float tend = 1.0; /* Final time */
    float y[1] = {1.0}; /* Initial condition */
    void *state;

    imsl_f_ode_runge_kutta_mgr (IMSL_ODE_INITIALIZE, &state, 0);
    imsl_f_ode_runge_kutta (neq, &t, tend, y, state, fcn);

    printf ("y[%f] = %f\n", t, y[0]);
    printf ("Error is: %e\n", exp( (double)(-tend) )-y[0]);
}

void fcn (int neq, float t, float y[], float yprime[]) {
    yprime[0] = -y[0];
}
```

User-supplied function to evaluate the right-hand side

y[1.000000] = 0.367879  
Error is: -9.149755e-09



# IMSL Nonlinear Equations Example – Root of a Equations

- **`zeros_sys_eqn`**
  - Solves a system of n nonlinear equations  $f(x) = 0$  using a modified Powell hybrid algorithm
- **Synopsis**
  - `float *imsl_f_zeros_sys_eqn (void fcn(), int n, ...)`
- **Required Arguments**
  - `void fcn (int n, float x[], float f[])` (Input/Output)
    - User-supplied function to evaluate the system of equations to be solved, where n is the size of x and f, x is the point at which the functions are evaluated, and f contains the computed function values at the point x
  - `int n` (Input)
    - The number of equations to be solved and the number of unknowns
- **Return Value**
  - A pointer to the vector x that is a solution of the system of equations. To release this space, use `free`



# IMSL C Exercise 19

## Nonlinear Equations Example



The example solves  $3 \times 3$  system of nonlinear equations

```
#include <imsl.h>
#include <stdio.h>
#include <math.h>
#define N 3
void fcn(int, float[], float[]);
void main() {
    float *x;
    float xguess[N] = {4.0, 4.0, 4.0};
    x = imsl_f_zeros_sys_eqn (fcn, N, IMSL_XGUESS, xguess, 0);
    imsl_f_write_matrix("The solution to the system is", 1, N, x, 0);
}
void fcn(int n, float x[], float f[]) {
    f[0] = x[0] + exp(x[0] - 1.0) + (x[1] + x[2]) * (x[1] + x[2]) - 27.0;
    f[1] = exp(x[1] - 2.0) / x[0] + x[2] * x[2] - 10.0;
    f[2] = x[2] + sin(x[1] - 2.0) + x[1] * x[1] - 7.0;
}
```

initial guess (4.0, 4.0, 4.0)

$$\begin{aligned}f_1(x) &= x_1 + e^{x_1-1} + (x_2 + x_3)^2 - 27 \\f_2(x) &= e^{x_2-2} / x_1 + x_3^2 - 10 \\f_3(x) &= x_3 + \sin(x_1 - 2) + x_2^2 - 7\end{aligned}$$

The solution to the system is

|   |   |   |
|---|---|---|
| 1 | 2 | 3 |
| 1 | 2 | 3 |



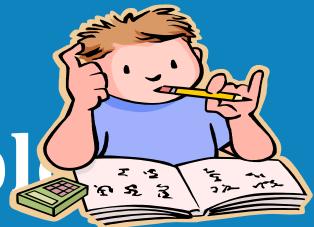
# IMSL Optimization Example - Nonlinearly Constrained Minimization

- **constrained\_nlp**
  - Solves a general nonlinear programming problem using a sequential equality constrained quadratic programming method
- **Synopsis**
  - `float *imsl_f_constrained_nlp (void fcn(), int m, int meq, int n, int ibtype, float xlb[], float xub[], ..., 0)`
- **Required Arguments**
  - `void fcn(int n, float x[], int iact, float *result, int *ierr)` (Input)
    - User supplied function to evaluate the objective function and constraints at a given point
  - `int m` (Input)
    - Total number of constraints
  - `int meq` (Input)
    - Number of equality constraints
  - `int n` (Input)
    - Number of variables
  - `int ibtype` (Input)
    - Scalar indicating the types of bounds on variables
  - `float xlb[]` (Input, Output, or Input/Output)
    - Array with n components containing the lower bounds on the variables
    - (Input, if ibtype = 0; output, if ibtype = 1 or 2; Input/Output, if ibtype = 3)
    - If there is no lower bound on a variable, then the corresponding xlb value should be set to `imsl_f_machine(8)`
  - `float xub[]` (Input, Output, or Input/Output)
    - Array with n components containing the upper bounds on the variables
    - (Input, if ibtype = 0; output, if ibtype 1 or 2; Input/Output, if ibtype = 3)
    - If there is no upper bound on a variable, then the corresponding xub value should be set to `imsl_f_machine(7)`
- **Return Value**
  - A pointer to the solution x of the nonlinear programming problem. To release this space, use `free`. If no solution can be computed, then `NULL` is returned



# IMSL C Exercise 20

## Nonlinear Equations Example



$$\min F(x) = (x_1 - 2)^2 + (x_2 - 1)^2$$

subject to

$$g_1(x) = x_1 - 2x_2 + 1 = 0$$

$$g_2(x) = -x_1^2 / 4 - x_2^2 + 1 \geq 0$$

```

#include "imsl.h"
#define M 2
#define ME 1
#define N 2
void grad(int n, float x[], int iact, float result[]);
void fcn(int n, float x[], int iact, float *result, int *ierr);
void main() {
    int ibtype = 0;
    float *x, ans[2];
    static float xlbt[N], xubt[N];
    xlbt[0] = xlbt[1] = imsl_f_machine (8);
    xubt[0] = xubt[1] = imsl_f_machine (7);
    x = imsl_f_constrained_nlp (fcn, M, ME, N, ibtype, xlbt, xubt, 0);
    imsl_f_write_matrix ("The solution is", 1, N, x, 0);
}

```

2 Constraints  
1 Equality constraints

```

void fcn (int n, float x[], int iact, float *result, int *ierr) {
    float tmp1, tmp2;
    tmp1 = x[0] - 2.0e0;
    tmp2 = x[1] - 1.0e0;
    switch (iact) {
        case 0:
            *result = tmp1 * tmp1 + tmp2 * tmp2;
            break;
        case 1:
            *result = x[0] - 2.0e0 * x[1] + 1.0e0;
            break;
        case 2:
            *result = -(x[0]*x[0]) / 4.0e0 - x[1]*x[1] + 1.0e0;
            break;
        default: ;
        break;
    }
    *ierr = 0;
    return;
}

```

The solution is

|        |        |
|--------|--------|
| 1      | 2      |
| 0.8229 | 0.9114 |

No lower and upper bound on a variable



# IMSL Regression Example - Multivariate Linear Regression

- **regression\_prediction**
  - Computes predicted values, confidence intervals, and diagnostics after fitting a regression model
- **Synopsis**
  - `float *imsls_f_regression_prediction (Imsls_f_regression *regression_info, int n_predict, float x[], ..., 0)`
- **Required Argument**
  - `Imsls_f_regression *regression_info` (Input)
    - Pointer to a structure of type `Imsls_f_regression` containing information about the regression fit. See `imsls_f_regression`
  - `int n_predict` (Input)
    - Number of rows in `x`
  - `float x[]` (Input)
    - Array of size `n_predict` by the number of independent variables containing the combinations of independent variables in each row for which calculations are to be performed
- **Return Value**
  - Pointer to an internally allocated array of length `n_predict` containing the predicted values



# IMSL C Exercise 20

## Regression Prediction



```
#include <imsls.h>
main() {
#define INTERCEPT 1
#define N_INDEPENDENT 4
#define N_OBSERVATIONS 13
#define N_COEFFICIENTS (INTERCEPT + N_INDEPENDENT)
#define N_DEPENDENT 1
float *y_hat, *coefficients;
Imsls_f_regression *regression_info;
float x[][N_INDEPENDENT] = {
    7.0, 26.0, 6.0, 60.0,
    1.0, 29.0, 15.0, 52.0,
    11.0, 56.0, 8.0, 20.0,
    11.0, 31.0, 8.0, 47.0,
    7.0, 52.0, 6.0, 33.0,
    11.0, 55.0, 9.0, 22.0,
    3.0, 71.0, 17.0, 6.0,
    1.0, 31.0, 22.0, 44.0,
    2.0, 54.0, 18.0, 22.0,
    21.0, 47.0, 4.0, 26.0,
    1.0, 40.0, 23.0, 34.0,
    11.0, 66.0, 9.0, 12.0,
    10.0, 68.0, 8.0, 12.0};
float y[] = {78.5, 74.3, 104.3, 87.6, 95.9, 109.2, 102.7, 72.5, 93.1, 115.9, 83.8, 113.3, 109.4};
coefficients = imsls_f_regression (N_OBSERVATIONS, N_INDEPENDENT, (float *)x, y, IMSLS_REGRESSION_INFO, &regression_info, 0);
y_hat = imsls_f_regression_prediction (regression_info, N_OBSERVATIONS, (float*)x, 0);
imsls_f_write_matrix("Predicted Responses", 1, N_OBSERVATIONS, y_hat, 0);
}
```

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_k x_{ik} + \varepsilon_i \quad i = 1, 2, \dots, n$$

| Predicted Responses |       |       |       |      |       |  |
|---------------------|-------|-------|-------|------|-------|--|
| 1                   | 2     | 3     | 4     | 5    | 6     |  |
| 78.5                | 72.8  | 106.0 | 89.3  | 95.6 | 105.3 |  |
| 104.1               | 75.7  | 91.7  | 115.6 | 81.8 | 112.3 |  |
| 13                  | 111.7 |       |       |      |       |  |

Fit the regression model  
Return regression coefficients

Pointer to a structure of type  
imsls\_f\_regression containing  
information about the regression fit



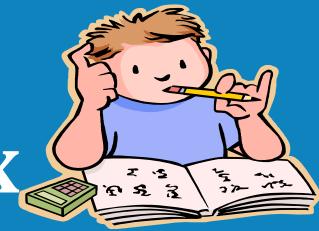
# IMSL Correlation and Covariance Example – Variance-Covariance Matrix

- **covariances**
  - Computes the sample variance-covariance or correlation matrix
- **Synopsis**
  - `float *imsls_f_covariances (int n_rows, int n_variables, float x[], ...,0)`
- **Required Arguments**
  - `int n_rows (Input)`
    - Number of rows in x
  - `int n_variables (Input)`
    - Number of variables
  - `float x[] (Input)`
    - Array of size `n_rows × n_variables` containing the data
- **Return Value**
  - If no optional arguments are used, `imsls_f_covariances` returns a pointer to an `n_variables × n_variables` array containing the sample variance-covariance matrix of the observations. The rows and columns of this array correspond to the columns of x



# IMSL C Exercise 21

## Variance-Covariance Matrix



```
#include <imsls.h>
#define N_VARIABLES 5
#define N_OBSERVATIONS 50
main() {
    float *covariances, *means;
    float x[] = {
        1.0, 5.1, 3.5, 1.4, .2, 1.0, 4.9, 3.0, 1.4, .2,
        1.0, 4.7, 3.2, 1.3, .2, 1.0, 4.6, 3.1, 1.5, .2,
        1.0, 5.0, 3.6, 1.4, .2, 1.0, 5.4, 3.9, 1.7, .4,
        1.0, 4.6, 3.4, 1.4, .3, 1.0, 5.0, 3.4, 1.5, .2,
        1.0, 4.4, 2.9, 1.4, .2, 1.0, 4.9, 3.1, 1.5, .1,
        1.0, 5.4, 3.7, 1.5, .2, 1.0, 4.3, 1.0, 4.8, 3.1, 1.6, .2, 1.0, 5.4, 3.4, 1.5, .4,
        1.0, 4.8, 3.0, 1.4, .1, 1.0, 4.1, 1.0, 5.2, 4.1, 1.5, .1, 1.0, 5.5, 4.2, 1.4, .2,
        1.0, 5.8, 4.0, 1.2, .2, 1.0, 5.1, 1.0, 4.9, 3.1, 1.5, .2, 1.0, 4.9, 3.1, 1.5, .2, 1.0, 5.0, 3.2, 1.2, .2,
        1.0, 5.4, 3.9, 1.3, .4, 1.0, 5.1, 1.0, 5.5, 3.5, 1.3, .2, 1.0, 4.9, 3.6, 1.4, .1,
        1.0, 5.7, 3.8, 1.7, .3, 1.0, 5.0, 1.0, 4.4, 3.0, 1.3, .2, 1.0, 5.1, 3.4, 1.5, .2,
        1.0, 5.4, 3.4, 1.7, .2, 1.0, 5.0, 1.0, 5.0, 3.5, 1.3, .3, 1.0, 5.0, 3.5, 1.3, .3,
        1.0, 4.6, 3.6, 1.0, .2, 1.0, 5.0, 1.0, 4.4, 3.2, 1.3, .2, 1.0, 5.0, 3.5, 1.6, .6,
        1.0, 4.8, 3.4, 1.9, .2, 1.0, 5.0, 1.0, 5.1, 3.8, 1.9, .4, 1.0, 4.8, 3.0, 1.4, .3,
        1.0, 5.0, 3.4, 1.6, .4, 1.0, 5.0, 1.0, 5.1, 3.8, 1.6, .2, 1.0, 4.6, 3.2, 1.4, .2,
        1.0, 5.2, 3.4, 1.4, .2, 1.0, 4.0, 1.0, 5.3, 3.7, 1.5, .2, 1.0, 5.0, 3.3, 1.4, .2};
    }
```

The default case: variances/covariances

|   | 1      | 2      | 3      | 4      | 5      |
|---|--------|--------|--------|--------|--------|
| 1 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| 2 |        | 0.1242 | 0.0992 | 0.0164 | 0.0103 |
| 3 |        |        | 0.1437 | 0.0117 | 0.0093 |
| 4 |        |        |        | 0.0302 | 0.0061 |
| 5 |        |        |        |        | 0.0111 |

IMSLS\_MISSING\_VALUE\_METHOD, int missing\_value\_method (Input)  
Method used to exclude missing values in x from the computations

```
covariances = imsls_f_covariances (N_OBSERVATIONS, N_VARIABLES, x, IMSLS_MISSING_VALUE_METHOD , 0, 0);
imsls_f_write_matrix ("The default case: variances/covariances", N_VARIABLES, N_VARIABLES, covariances, IMSLS_PRINT_UPPER, 0);
}
```



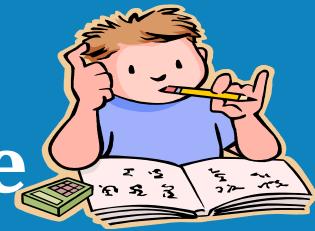
# IMSL Correlation and Covariance Example – Pooled Variance-Covariance

- **pooled\_covariances**
  - Compute a pooled variance-covariance from the observations
- **Synopsis**
  - float \*imsls\_f\_pooled\_covariances (int n\_rows, int n\_variables, float \*x, int n\_groups, ..., 0)
- **Required Argument**
  - int n\_rows (Input)
    - Number of rows observations in the input matrix x
  - int n\_variables (Input)
    - Number of variables to be used in computing the covariance matrix
  - float \*x (Input)
    - A n\_rows x n\_variables + 1 matrix containing the data. The first n\_variables columns correspond to the variables, and the last column (column n\_variables must contain the group numbers)
  - int n\_groups (Input)
    - Number of groups in the data
- **Return Value**
  - Matrix of size n\_variables by n\_variables containing the matrix of covariances
- **Optional Arguments**
  - IMSLS\_IDO, int ido (Input)
    - Processing option



# IMSL C Exercise 22

## Pooled Variance-Covariance



The example computes a pooled variance-covariance matrix for the Fisher iris data. To illustrate the use of the ido argument, multiple calls to `imsls_f_pooled_covariances` are made

```
#include <stdio.h>
#include <stdlib.h>
#include <imsls.h>
main() {
    int nobs = 150;
    int nvar = 4;
    int n_groups = 3;
    int igrp = 0;
    static int ind[4] = {1, 2, 3, 4};
    int ifrq = -1;
    int iwt = -1;
    float *x, cov[16];
    float *means;
    int i;
    x = imsls_f_data_sets(3, 0);
    imsls_f_pooled_covariances(0, nvar, x, n_groups, IMSLS_IDO, 1, IMSLS_RETURN_USER, cov, IMSLS_X_INDICES, igrp, ind, ifrq, iwt, 0);
    for (i=0;i<15;i++) {
        imsls_f_pooled_covariances(10, nvar, (x+i*50), n_groups, IMSLS_IDO, 2, IMSLS_RETURN_USER, cov, IMSLS_X_INDICES, igrp, ind, ifrq, iwt, 0);
    }
    imsls_f_pooled_covariances(0, nvar, x, n_groups, IMSLS_IDO, 3, IMSLS_RETURN_USER, cov, IMSLS_X_INDICES, igrp, ind, ifrq, iwt,
        IMSLS_MEANS, &means, 0);
    imsls_f_write_matrix("Pooled Covariance Matrix", nvar, nvar, cov, 0);
    imsls_f_write_matrix("Means", n_groups, nvar, means, 0);
    free(means);
    free(x);
}
```

Fisher iris  
150 observations and 5 variables

IDO = 1  
First invocation with this data

IDO = 2  
Intermediate invocation

IDO = 3  
All statistics are updated for the n\_rows observations

| Pooled Covariance Matrix |        |        |        |        |
|--------------------------|--------|--------|--------|--------|
|                          | 1      | 2      | 3      | 4      |
| 1                        | 0.2650 | 0.0927 | 0.1675 | 0.0384 |
| 2                        | 0.0927 | 0.1154 | 0.0552 | 0.0327 |
| 3                        | 0.1675 | 0.0552 | 0.1852 | 0.0427 |
| 4                        | 0.0384 | 0.0327 | 0.0427 | 0.0419 |

| Means |       |       |       |       |
|-------|-------|-------|-------|-------|
|       | 1     | 2     | 3     | 4     |
| 1     | 5.006 | 3.428 | 1.462 | 0.246 |
| 2     | 5.936 | 2.770 | 4.260 | 1.326 |
| 3     | 6.588 | 2.974 | 5.552 | 2.026 |

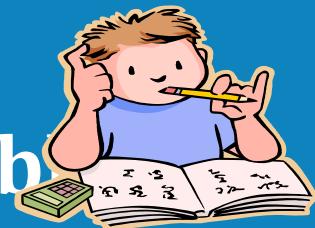
# IMSL Analysis of Variance and Designed Experiments Example – One-Way Classification Model

- **anova\_oneway**
  - Analyzes a one-way classification model
- **Synopsis**
  - float imsIs\_f\_anova\_oneway (int n\_groups, int n[], float y[], ..., 0)
- **Required Arguments**
  - int n\_groups (Input)
    - Number of groups
  - int n[] (Input)
    - Array of length n\_groups containing the number of responses for each group
  - float y[] (Input)
    - Array of length n [0] + n [1] + ... + n [n\_group -1] containing the responses for each group
- **Return Value**
  - The p-value for the F-statistic



# IMSL C Exercise 23

## Output One-Way ANOVA Tab



This example computes a one-way analysis of variance for data discussed by Searle (1971, Table 5.1, pp. 165~179). The responses are plant weights for six plants of three different types—three normal, two off-types, and one aberrant. The responses are given by type of plant in the right table.

| Normal | Off-Type | Aberrant |
|--------|----------|----------|
| 101    | 84       | 32       |
| 105    | 88       |          |
| 94     |          |          |

\* \* \* Analysis of Variance \* \* \*

|   |         |
|---|---------|
| degrees of freedom for among groups     | 2.00    |
| degrees of freedom for within groups    | 3.00    |
| total (corrected) degrees of freedom    | 5.00    |
| sum of squares for among groups         | 3480.00 |
| sum of squares for within groups        | 70.00   |
| total (corrected) sum of squares        | 3550.00 |
| among mean square                       | 1740.00 |
| within mean square                      | 23.33   |
| F-statistic                             | 74.57   |
| p-value                                 | 0.00    |
| R-squared (in percent)                  | 98.03   |
| adjusted R-squared (in percent)         | 96.71   |
| est. standard deviation of within error | 4.83    |
| overall mean of y                       | 84.00   |
| coefficient of variation (in percent)   | 5.75    |

```
#include <imsls.h>
main() {
    int n_groups=3;
    int n[] = {3, 2, 1};
    float y[] = {101.0, 105.0, 94.0, 84.0, 88.0, 32.0}; ←
    float p_value;
    float *anova_table;
    char *labels[] = {
        "degrees of freedom for among groups", "degrees of freedom for within gro",
        "total (corrected) degrees of freedom", "sum of squares for among groups",
        "sum of squares for within groups", "total (corrected) sum of squares",
        "among mean square", "within mean square", "F-statistic",
        "p-value", "R-squared (in percent)", "adjusted R-squared (in percent)",
        "est. standard deviation of within error", "overall mean of y", "coefficient of variation (in percent)"};

    p_value = imsls_f_anova_oneway(n_groups, n, y, IMSLS_ANOVA_TABLE, &anova_table, 0);
    imsls_f_write_matrix(" * * * Analysis of Variance * * *\n", 15, 1, anova_table, IMSLS_ROW_LABELS, labels, IMSLS_WRITE_FORMAT, "%9.2f", 0);
}
```

# IMSL Nonparametric Statistics

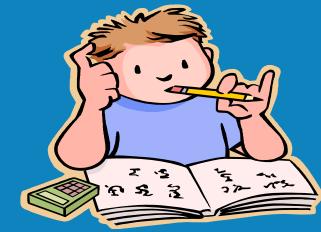
## Example – Kruskal Wallis Test

- **kruskal\_wallis\_test**
  - Performs a Kruskal-Wallis test for identical population medians
- **Synopsis**
  - float \*imsls\_f\_kruskal\_wallis\_test (int n\_groups, int ni[], float y[], ..., 0)
- **Required Arguments**
  - int n\_groups (Input)
    - Number of groups
  - int ni[] (Input)
    - Array of length n\_groups containing the number of responses for each of the n\_groups groups
  - float y[] (Input)
    - Array of length ni[0] + ... + ni[n\_groups-1] that contains the responses for each of the n\_groups groups. y must be sorted by group, with the ni[0] observations in group 1 coming first, the ni[1] observations in group two coming second, and so on
- **Return Value**
  - Array of length 4 containing the Kruskal-Wallis statistics
    - I stat[]
    - 0 Kruskal-Wallis H statistic
    - 1 Asymptotic probability of a larger H under the null hypothesis of identical population medians
    - 2 H corrected for ties
    - 3 Asymptotic probability of a larger H (corrected for ties) under the null hypothesis of identical populations
- **Optional Arguments**
  - IMSLS\_FUZZ, float fuzz (Input)
    - Constant used to determine ties in y. If (after sorting) |y[i] – y[i + 1]| is less than or equal to fuzz, then a tie is counted
  - IMSLS\_RETURN\_USER, float stat[] (Output)
    - User defined array for storage of Kruskal-Wallis statistics



# IMSL C Exercise 24

## Kruskal Wallis Test



The example is taken from Conover (1980, page 231). The data represents the yields per acre of four different methods for raising corn. Since  $H = 25.5$ , the four methods are clearly different. The warning error is always printed when the Beta approximation is used, unless printing for warning errors is turned off

```
#include <imsls.h>
void main() {
    int ngroup = 4, ni[] = {9, 10, 7, 8};
    float y[] = {83., 91., 94., 89., 89., 96., 91., 92., 90., 91., 90.,
    81., 83., 84., 83., 88., 91., 89., 84., 101., 100., 91.,
    93., 96., 95., 94., 78., 82., 81., 77., 79., 81., 80., 81.};
    float fuzz = .001, stat[4];
    char *rlabel[] = {"H (no ties) =", "Prob (no ties) =", "H (ties) =", "Prob (ties) ="};
    imsls_f_kruskal_wallis_test(ngroup, ni, y, IMSLS_FUZZ, fuzz, IMSLS_RETURN_USER, stat, 0);
    imsls_f_write_matrix(" ", 4, 1, stat, IMSLS_ROW_LABELS, rlabel, 0);
}
```

```
*** WARNING ERROR from imsls_kruskal_wallis_test. The chi-squared degrees
*** of freedom are less than 5, so the Beta approximation is used.
H (no ties)          =
Prob (no ties)        =
H (ties)              =
Prob (ties)           =      25.46
                                0.00
                                25.63
                                0.00
```



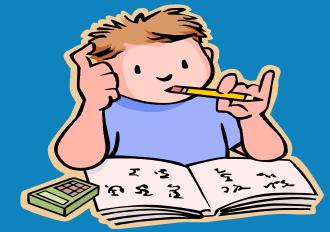
# IMSL Multivariate Analysis Example – K-Means Cluster Analysis

- **cluster\_k\_means**
  - Performs a K-means (centroid) cluster analysis
- **Synopsis**
  - `int *imsls_f_cluster_k_means (int n_observations, int n_variables, float x[], int n_clusters, float cluster_seeds, ..., 0)`
- **Required Arguments**
  - `int n_observations (Input)`
    - Number of observations
  - `int n_variables (Input)`
    - Number of variables to be used in computing the metric
  - `float x[] (Input)`
    - Array of length `n_observations × n_variables` containing the observations to be clustered
  - `int n_clusters (Input)`
    - Number of clusters
  - `float cluster_seeds[] (Input)`
    - Array of length `n_clusters × n_variables` containing the cluster seeds, i.e., estimates for the cluster centers
- **Return Value**
  - The cluster membership for each observation is returned



# IMSL C Exercise 25

## K-Means Cluster Analysis



This example performs K-means cluster analysis on Fisher's iris data, which is obtained by function [imsls\\_f\\_data\\_sets](#). The initial cluster seed for each iris type is an observation known to be in the iris type

```
#include <stdio.h>
#include <imsls.h>
main() {
#define N_OBSERVATIONS 150
#define N_VARIABLES 4
#define N_CLUSTERS 3
float x[N_OBSERVATIONS][5];
float cluster_seeds[N_CLUSTERS][N_VARIABLES];
float cluster_means[N_CLUSTERS][N_VARIABLES];
float cluster_ssq[N_CLUSTERS];
int cluster_variables[N_VARIABLES] = {1, 2, 3, 4};
int cluster_counts[N_CLUSTERS];
int cluster_group[N_OBSERVATIONS];
int i;
imsls_f_data_sets(3, IMSLS_RETURN_USER, x, ...);
for (i=0; i<N_VARIABLES; i++) {
cluster_seeds[0][i] = x[0][i+1];
cluster_seeds[1][i] = x[50][i+1];
cluster_seeds[2][i] = x[100][i+1];
}
imsls_f_cluster_k_means(N_OBSERVATIONS, N_VARIABLES, (float*)x, N_CLUSTERS, (float*)cluster_seeds,
IMSLS_X_COL_DIM, 5, IMSLS_CLUSTER_VARIABLE_COLUMNS, cluster_variables, IMSLS_CLUSTER_COUNTS_USER,
cluster_counts, IMSLS_CLUSTER_MEANS_USER, cluster_means, IMSLS_CLUSTER_SSQ_USER, cluster_ssq,
IMSLS_RETURN_USER, cluster_group, 0);
}
```

Fisher iris  
 150 observations and 5 variables

4 Variables  
 150 Observations  
 3 Clusters

```
imsls_f_write_matrix("Cluster Means", N_CLUSTERS, N_VARIABLES, (float*)cluster_means, 0);
imsls_f_write_matrix("Cluster Sum of Squares", 1, N_CLUSTERS, cluster_ssq, 0);
imsls_i_write_matrix("# Observations in Each Cluster", 1, N_CLUSTERS, cluster_counts, 0);
}
```

| Cluster Means |       |       |       |       |
|---------------|-------|-------|-------|-------|
|               | 1     | 2     | 3     | 4     |
| 1             | 5.006 | 3.428 | 1.462 | 0.246 |
| 2             | 5.902 | 2.748 | 4.394 | 1.434 |
| 3             | 6.850 | 3.074 | 5.742 | 2.071 |

| Cluster Sum of Squares |       |       |       |
|------------------------|-------|-------|-------|
|                        | 1     | 2     | 3     |
| 1                      | 15.15 | 39.82 | 23.88 |

| # Observations in Each Cluster |    |    |    |
|--------------------------------|----|----|----|
|                                | 1  | 2  | 3  |
| 1                              | 50 | 62 | 38 |



# IMSL C Numerical Library Useful Information

- Calling IMSL CNL from VB or Excel
  - <http://www.vni.com/products/imsl/c/visualbasic.html>
- Calling IMSL Fortran Library from C Language
  - <http://www.vni.com/tech/imsl/8902.pdf>
- Calling IMSL CNL for MVS version from Borland C++ Builder
  - [http://www.vni.com/tech/imsl/bcc55\\_cnldll.zip](http://www.vni.com/tech/imsl/bcc55_cnldll.zip)
- Calling IMSL CNL from C Language
  - <http://www.vni.com.tw/tw/tech/imsl/>

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# Open Discussion

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# Thanks!

$$\min \frac{1}{2} \sum_{i=1}^n f_i(x)$$

# Appendix

## IMSL Matrix Storage Modes



# IMSL CNL Matrix Storage Modes 1/10

- IMSL CNL functions require input consisting of matrix dimension values and all values for the matrix entries
- The values are stored in row-major order in the arrays
- Each function processes the input array and typically returns a pointer to a “result”



# IMSL CNL

## Matrix Storage Modes 2/10

- General Mode
  - $n \times n$  matrix
  - float, double, f\_complex, d\_complex
- Rectangular Mode
  - $m \times n$  matrix
  - float, double, f\_complex, d\_complex
- Symmetric Mode
  - $A^T = A$
  - $n \times n$  matrix
  - float, double



# IMSL CNL Matrix Storage Modes 3/10

- Hermitian Mode

- n x n matrix  $A^H = \bar{A}^T = A$  ( $\bar{A}^T$  is the complex conjugate of A)
- f\_complex, d\_complex



# IMSL CNL Matrix Storage Modes 4/10

- Sparse Coordinate Storage Format
  - Only the nonzero of a sparse matrix need to be communicated to a function

```
typedef struct{
    int row;
    int col;
    float val;
} Imsl_f_sparse_elem;
```

```
typedef struct {
    int row;
    int col;
    f_complex val;
} Imsl_c_sparse_elem;
```



# IMSL CNL Matrix Storage Modes 5/10

```
#include <imsl.h>
main() {
    Imsl_f_sparse_elem a[] = {
        {0, 0, 2.0},
        {1, 1, 9.0},
        {1, 2, -3.0},
        {1, 3, -1.0},
        {2, 2, 5.0},
        .... };

    Imsl_f_sparse_elem b[15];
    b[0].row = b[0].col = 0;
    b[1].row = b[1].col = 1;
    b[2].row = 1; b[2].col = 2;
    b[3].row = 1; b[3].col = 3;
    b[4].row = b[4].col = 2;
    ....
};
```

$$A = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 9 & -3 & -1 & 0 & 0 \\ 0 & 0 & 5 & 0 & 0 & 0 \\ -2 & 0 & 0 & -7 & -1 & 0 \\ -1 & 0 & 0 & -5 & 1 & -3 \\ -1 & -2 & 0 & 0 & 0 & 6 \end{bmatrix}$$

|     |   |   |    |    |   |    |    |    |    |    |   |    |    |    |   |
|-----|---|---|----|----|---|----|----|----|----|----|---|----|----|----|---|
| row | 0 | 1 | 1  | 1  | 2 | 3  | 3  | 3  | 4  | 4  | 4 | 4  | 5  | 5  | 5 |
| col | 0 | 1 | 2  | 3  | 2 | 0  | 3  | 4  | 0  | 3  | 4 | 5  | 0  | 1  | 5 |
| val | 2 | 9 | -3 | -1 | 5 | -2 | -7 | -1 | -1 | -5 | 1 | -3 | -1 | -2 | 6 |

b[0].val = 2.0;  
 b[1].val = 9.0;  
 b[2].val = -3.0;  
 b[3].val = -1.0;  
 b[4].val = 5.0;



# IMSL CNL Matrix Storage Modes 6/10

- Band Storage Format
  - M x N matrix
  - All of nonzero elements close to the main diagonal
  - $A_{ij} = 0$  if  $i-j < nlca$  or  $j-i > nuca$
  - $M = nlca + nuca + 1$
  - $nlca$  lower codiagonals,  $nuca$  upper codiagonals are stored in the rows of an array of size  $m \times N$
  - The elements are stored in the same column of the array as type are in the matrix



# IMSL CNL Matrix Storage Modes 7/10

$$A = \begin{bmatrix} A_{0,0} & A_{0,1} & A_{0,2} & 0 & 0 \\ A_{1,0} & A_{1,1} & A_{1,2} & A_{1,3} & 0 \\ 0 & A_{2,1} & A_{2,2} & A_{2,3} & A_{2,4} \\ 0 & 0 & A_{3,2} & A_{3,3} & A_{3,4} \\ 0 & 0 & 0 & A_{4,3} & A_{4,4} \end{bmatrix}$$

data be arranged as

$$\begin{bmatrix} 0 & 0 & A_{0,2} & A_{1,3} & A_{2,4} \\ 0 & A_{0,1} & A_{1,2} & A_{2,3} & A_{3,4} \\ A_{0,0} & A_{1,1} & A_{2,2} & A_{3,3} & A_{4,4} \\ A_{1,0} & A_{2,1} & A_{3,2} & A_{4,3} & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 10 & 1 & 0 & 0 & 0 \\ 5 & 20 & 2 & 0 & 0 \\ 0 & 6 & 30 & 3 & 0 \\ 0 & 0 & 7 & 40 & 4 \\ 0 & 0 & 0 & 8 & 50 \end{bmatrix}$$

declaration

```
float a[] = {0.0, 1.0, 2.0, 3.0,
4.0, 10.0, 20.0, 30.0, 40.0, 50.0,
5.0, 6.0, 7.0, 8.0, 0.0};
```



## IMSL CNL Matrix Storage Modes 8/10

- Compressed Sparse Column (CSC) format
  - The Harwell-Boeing Sparse Matrix Collection is a set of standard test matrices arising from problems in linear systems, least squares, and eigenvalue calculations
- The scheme is column oriented, with each column held as a sparse vector
- Data for each column are stored consecutively and in order



# IMSL CNL Matrix Storage Modes 9/10

- colptr: location of first entry
- rowind: rwo indices
- values: nonzero entries

$$\begin{bmatrix} 1 & -3 & 0 & -1 & 0 \\ 0 & 0 & -2 & 0 & 3 \\ 2 & 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & -4 & 0 \\ 5 & 0 & -5 & 0 & 6 \end{bmatrix}$$

| Subscripts | 0 | 1 | 2 | 3 | 4  | 5  | 6  | 7  | 8  | 9 | 10 |
|------------|---|---|---|---|----|----|----|----|----|---|----|
| colptr     | 0 | 3 | 5 | 7 | 9  | 11 |    |    |    |   |    |
| rowind     | 0 | 4 | 2 | 3 | 0  | 1  | 4  | 0  | 3  | 4 | 1  |
| values     | 1 | 5 | 2 | 4 | -3 | -2 | -5 | -1 | -4 | 6 | 3  |



# IMSL CNL Matrix Storage Modes 10/10

- Linear Systems
  - Linear equations with full matrices
    - lin\_sol\_gen
  - Linear equations with band matrices
    - lin\_sol\_gen\_band
  - Linear equations with general sparse matrices
    - lin\_sol\_gen\_coordinate
  - :



## IMSL C on hpc.ustc.edu.cn

- telnet to 202.38.64.91
- Account: train
- Password: imsl
- IMSL installed path: /opt/vni